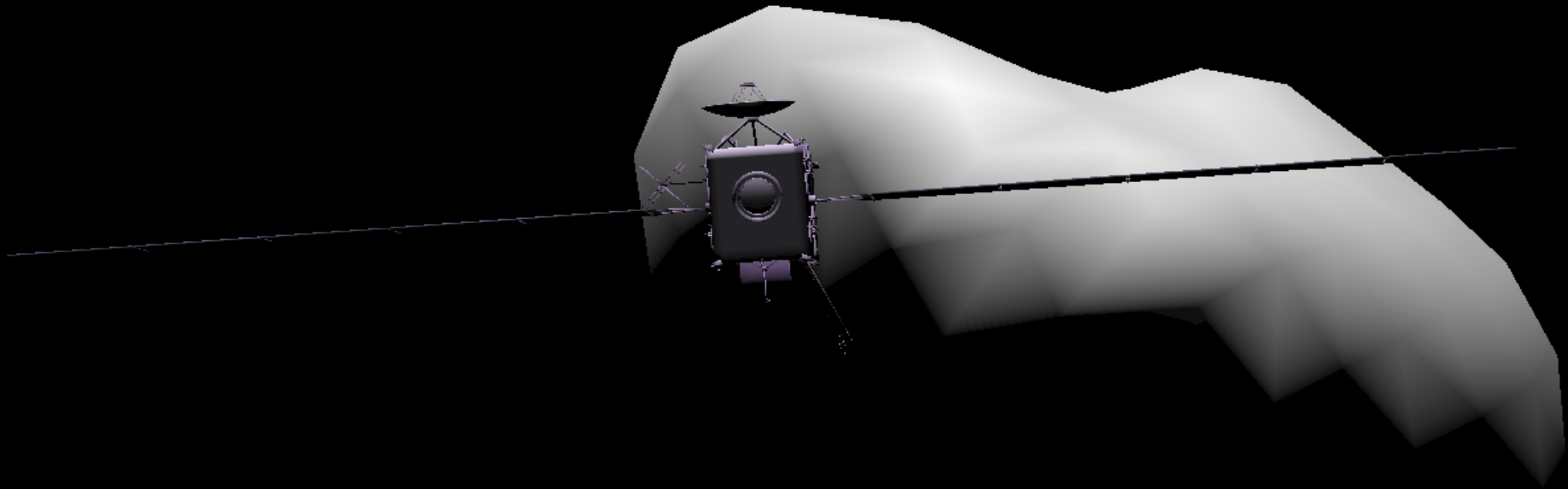


Review of
ro-c-osinac_osiwac-5-67p-shape-v1.0



Björn Grieger
Trajectory Planning and Simulation
Aurora Technology, B. V.
ESAC, Madrid, Spain

1

Editorial comments

Lower case file names

```
aareadme.txt  
catalog  
data  
document  
index  
voldesc.cat
```

All directory and file names are lower case, while the PDS standard requires them to be upper case.

There is, at this point, only one source of shape models - the 3-D Modeling group of the OSIRIS science team.

How about the MOC shape models?

aareadme.txt:

The modeling group has produced two different models using stereophotoclinometry techniques, [...]

spc_model_info.asc:

The shape models [...] were developed [...] from two different techniques: Stereophotoclinometry (SPC) and Multi-resolution photoclinometry by deformation (MSPCD).

Besides just citing the relevant publications, it would be helpful to have a brief description of both techniques directly available in the data set:

- How do stereophotoclinometry techniques work in general?
- How does the applied SPC technique work in particular?
- How does the applied MSPCD technique work in particular?

2

Consistency between plate
shape models and provided
rendered images

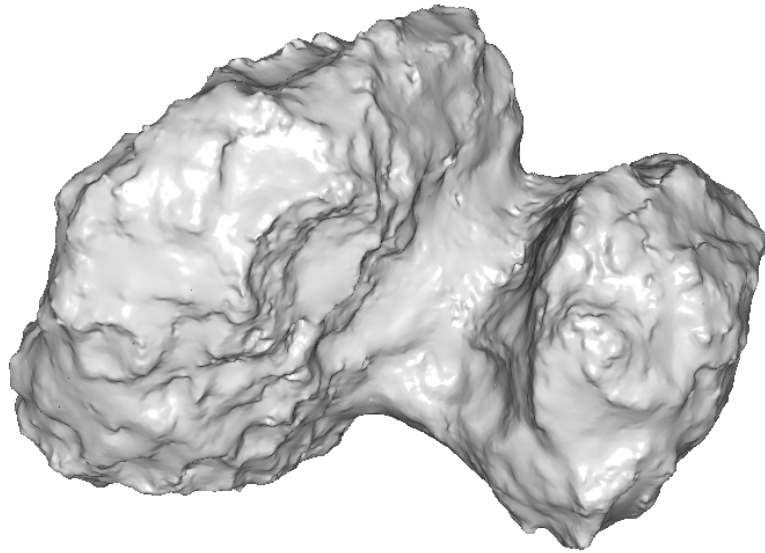
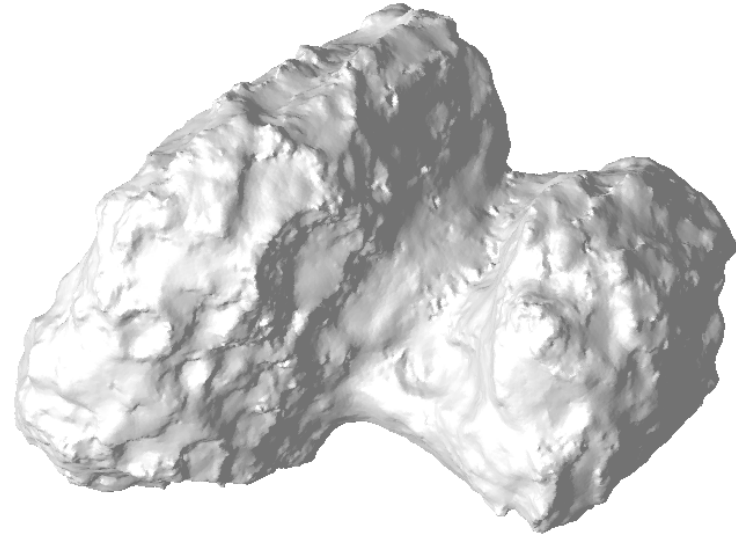


Image from data set



Rendered
Orthographic projection

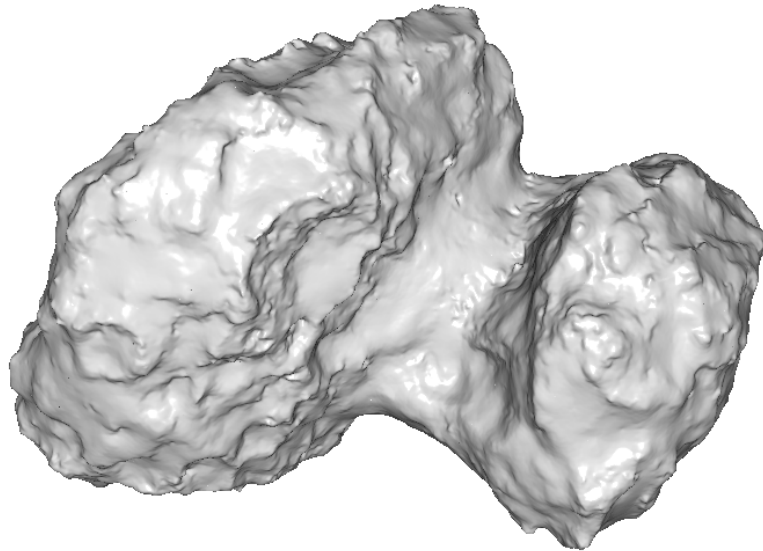
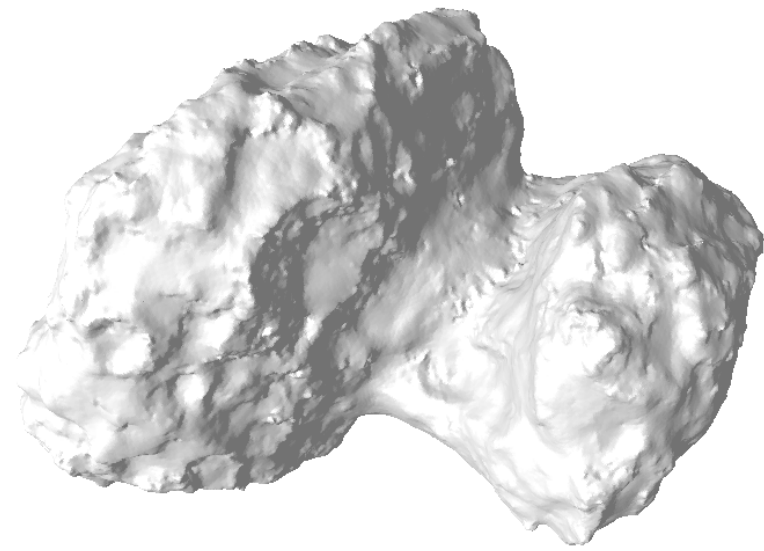


Image from data set



Rendered
Perspective projection
Distance 7.5 km
FOV 50°

- Camera parameters shall be provided.
- Surface model and illumination should be provided.

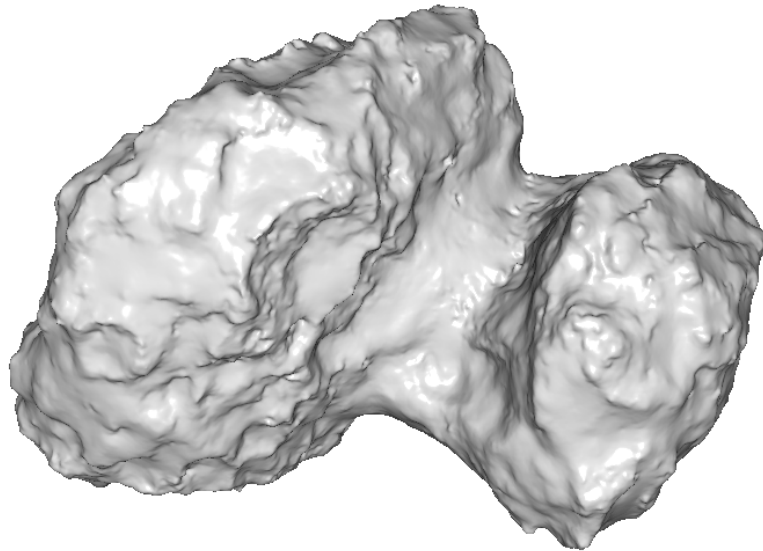
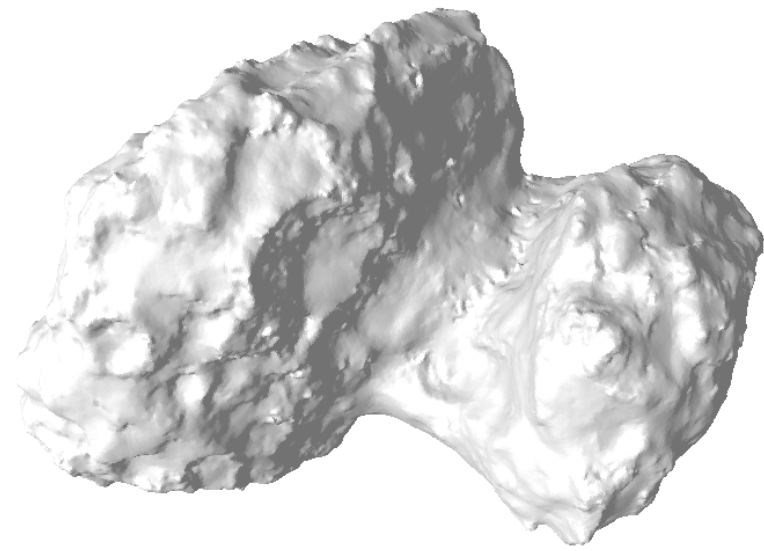


Image from data set



Rendered
Perspective projection
Distance 7.5 km
FOV 50°

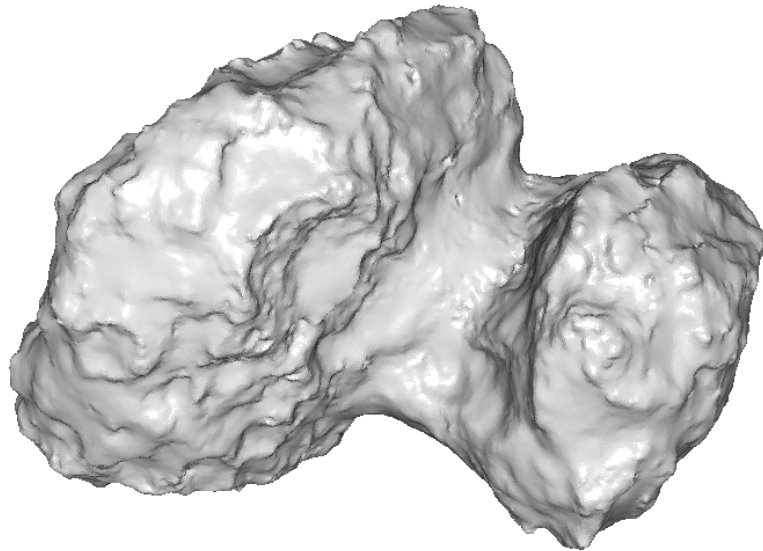
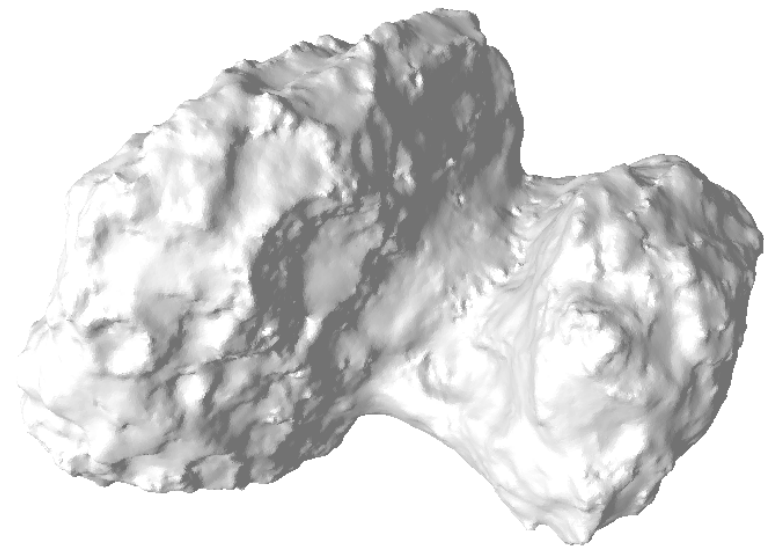


Image from data set



Rendered
Perspective projection
Distance 7.5 km
FOV 50°

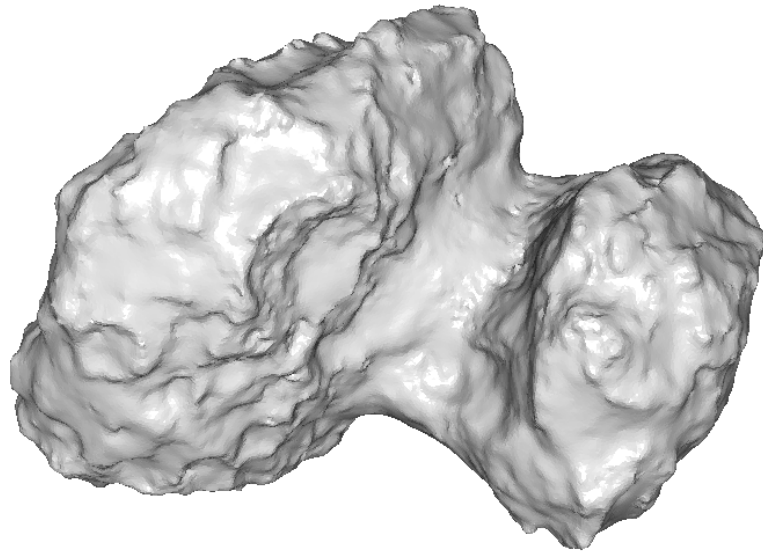
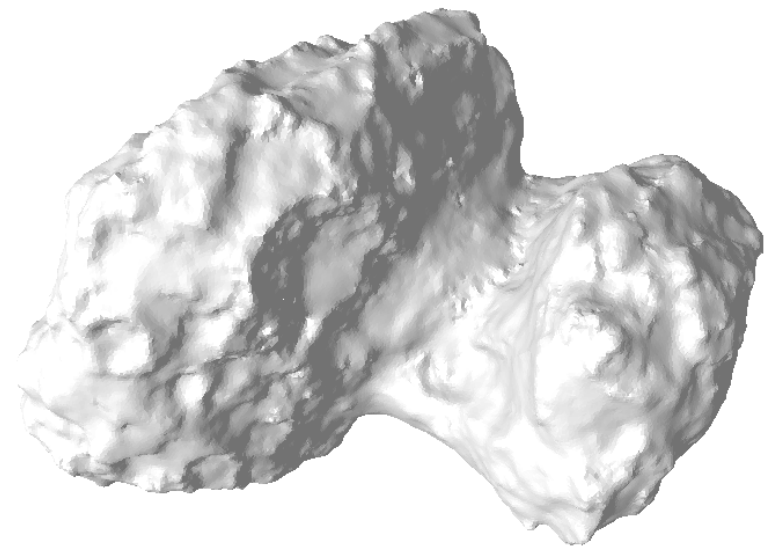


Image from data set



Rendered
Perspective projection
Distance 7.5 km
FOV 50°

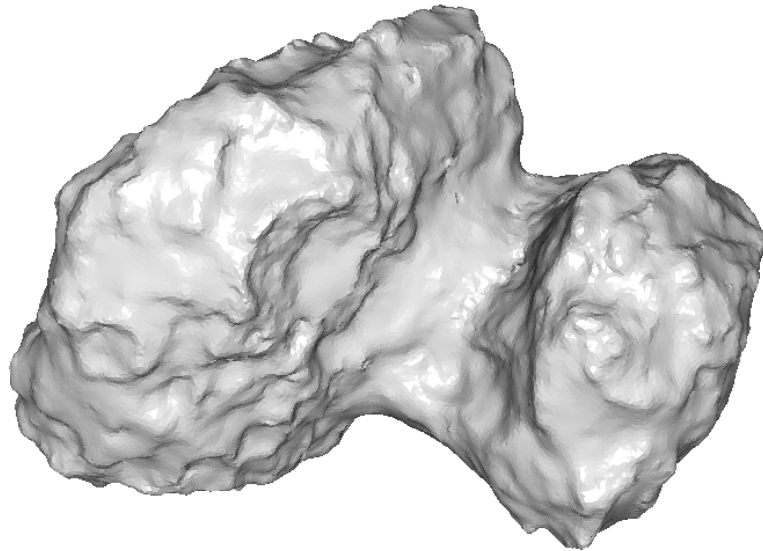
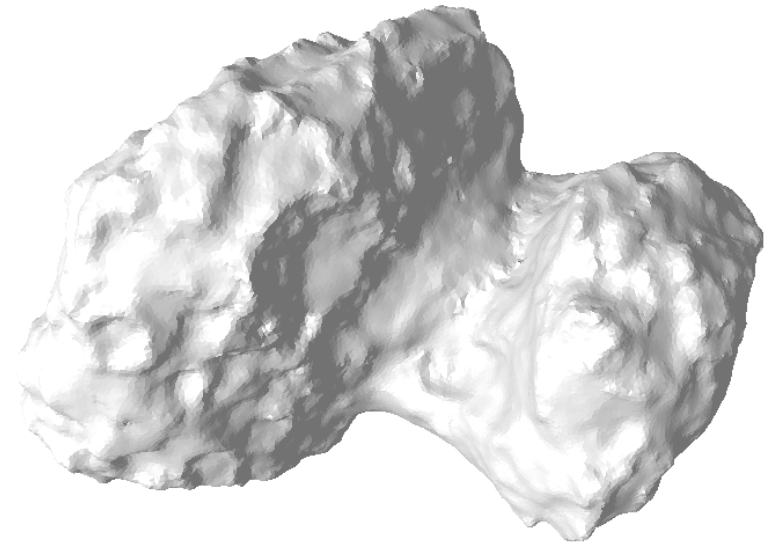


Image from data set



Rendered
Perspective projection
Distance 7.5 km
FOV 50°

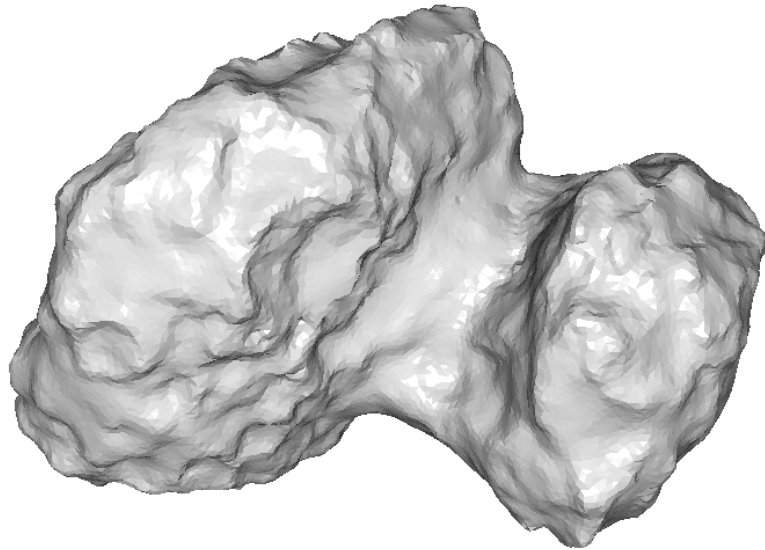
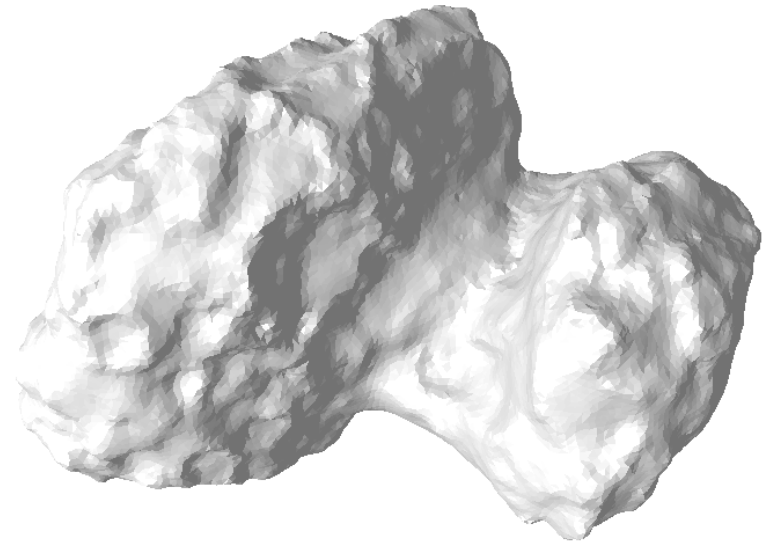


Image from data set



Rendered
Perspective projection
Distance 7.5 km
FOV 50°

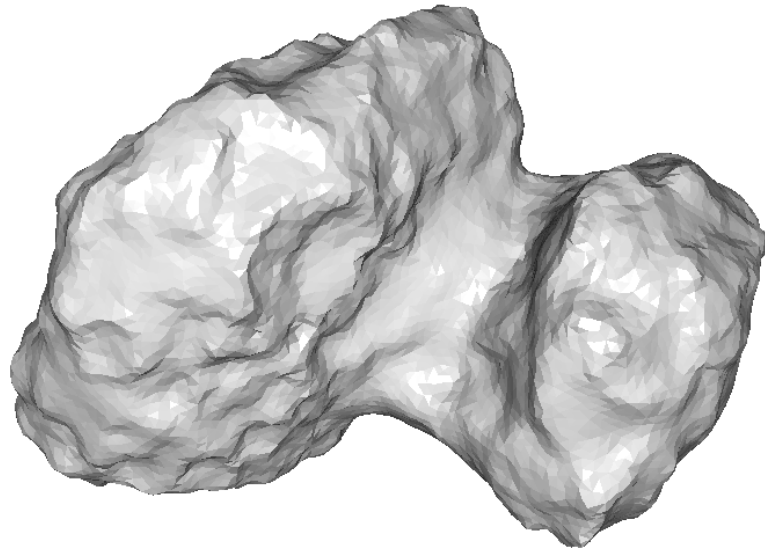
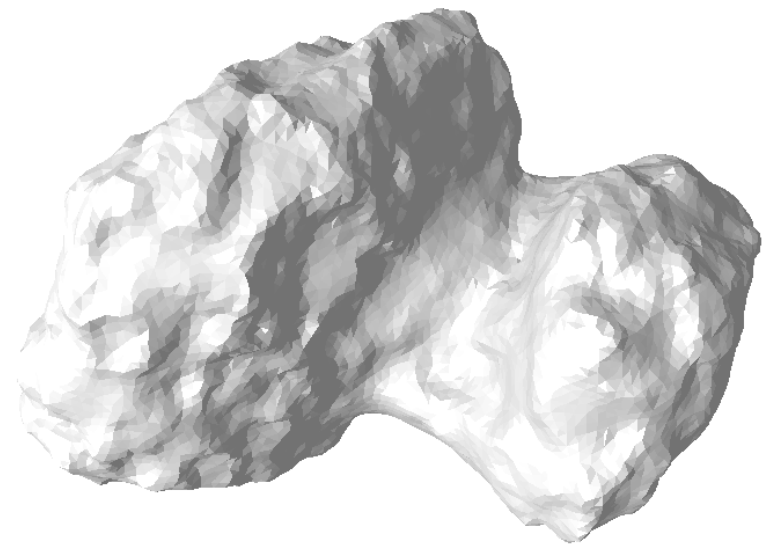


Image from data set



Rendered
Perspective projection
Distance 7.5 km
FOV 50°

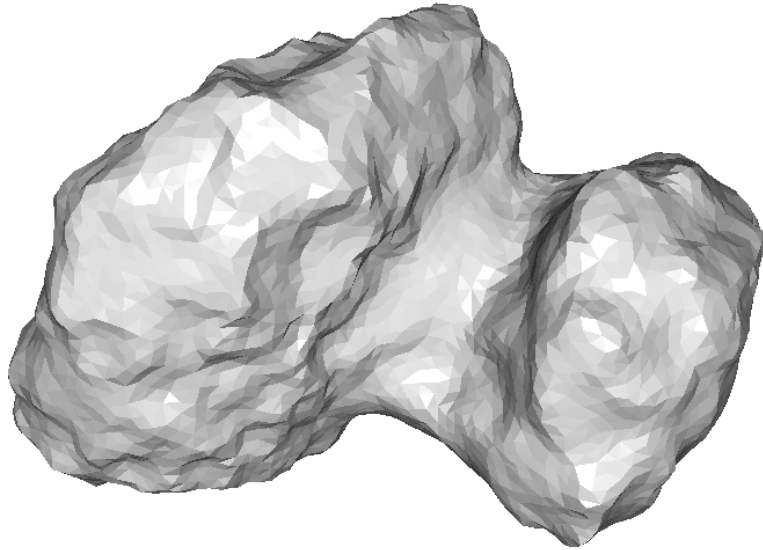
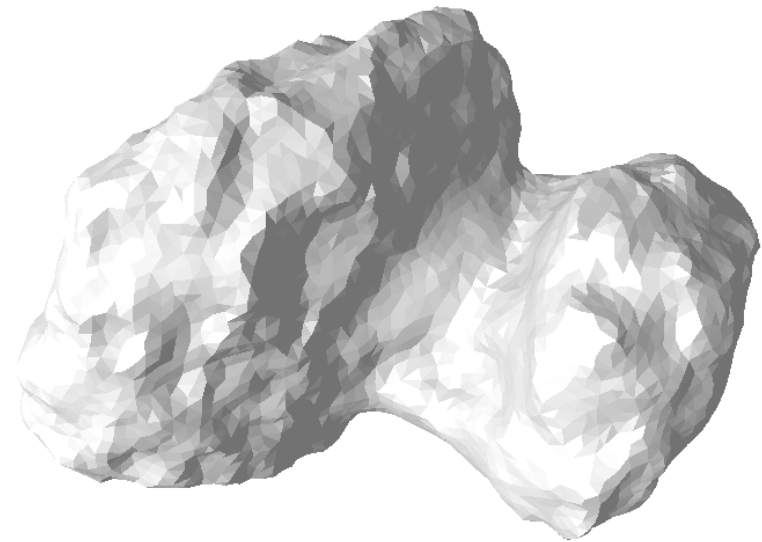


Image from data set



Rendered
Perspective projection
Distance 7.5 km
FOV 50°

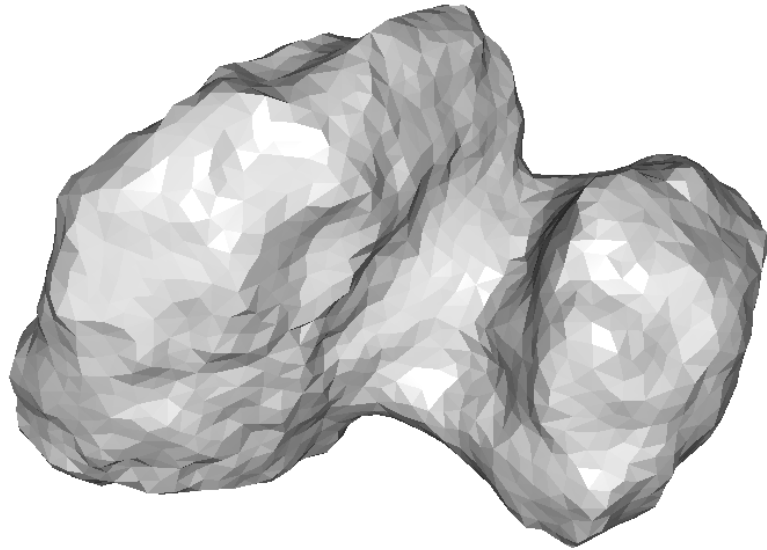
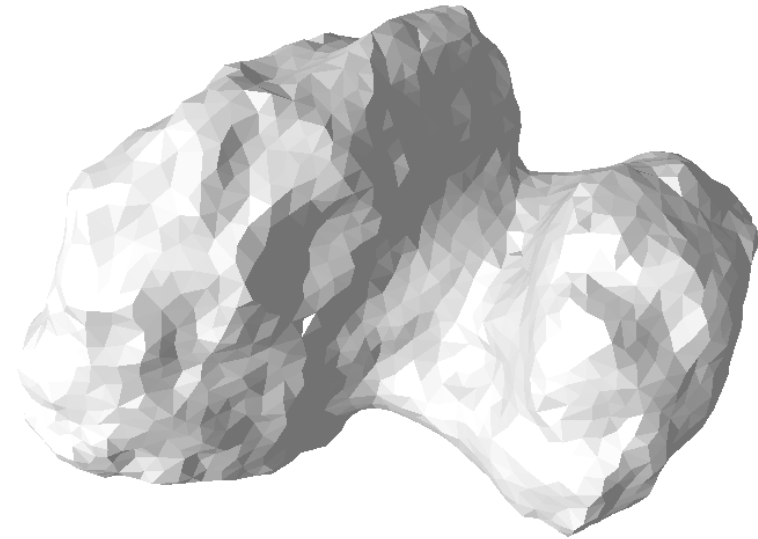


Image from data set



Rendered
Perspective projection
Distance 7.5 km
FOV 50°

→ The images are consistent with the plate shape models.

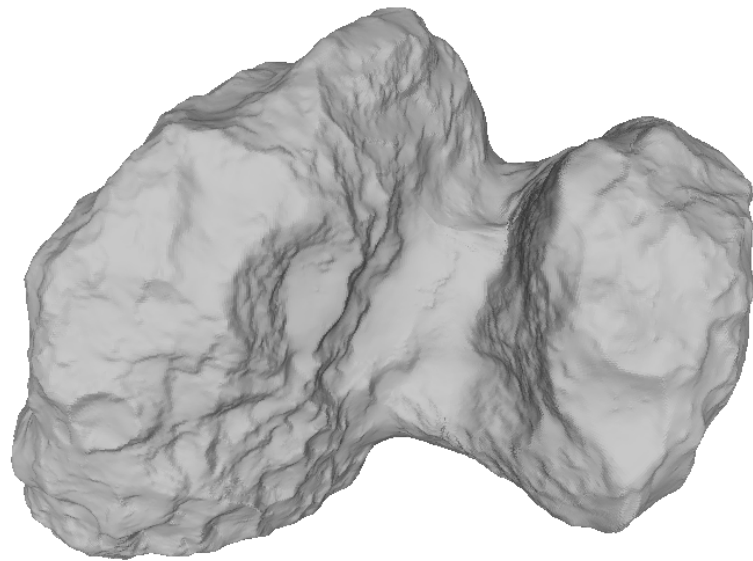
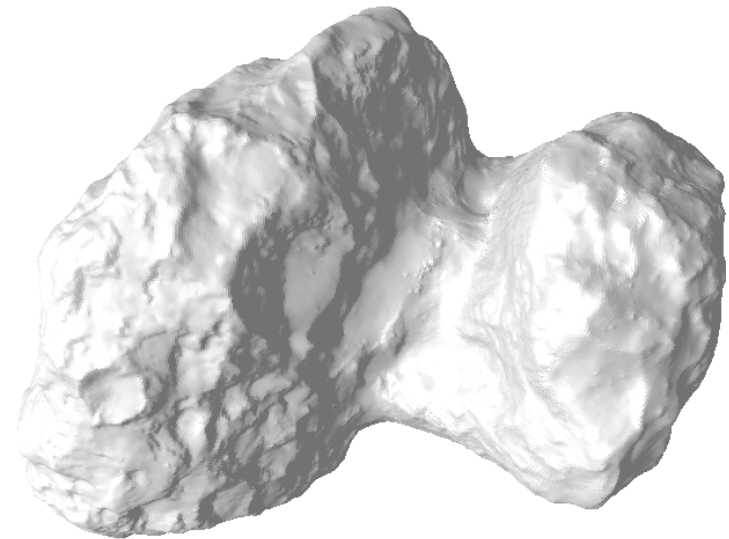


Image from data set



Rendered
Perspective projection
Distance 7.5 km
FOV 50°

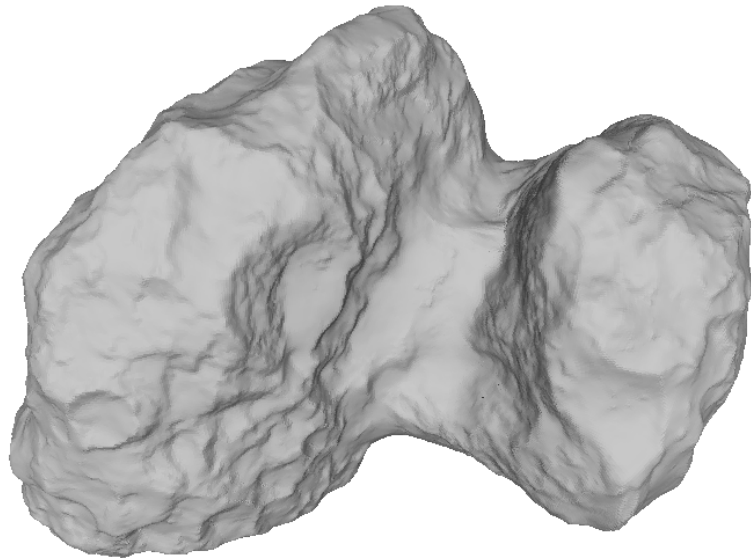
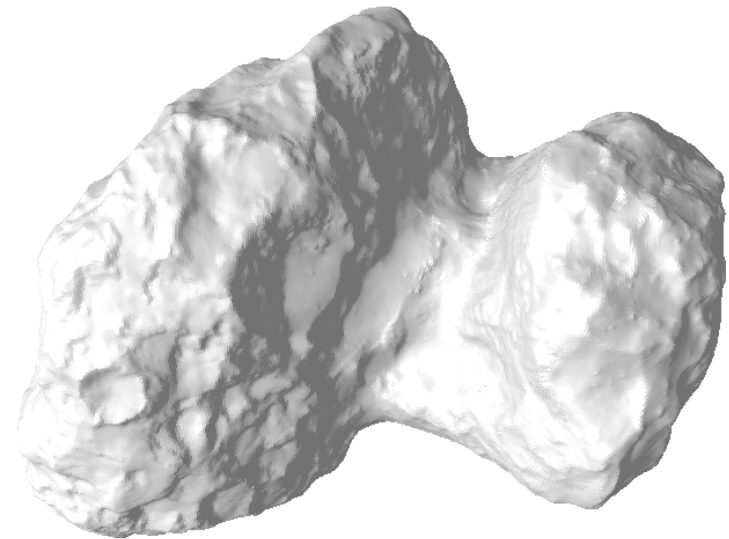


Image from data set



Rendered
Perspective projection
Distance 7.5 km
FOV 50°

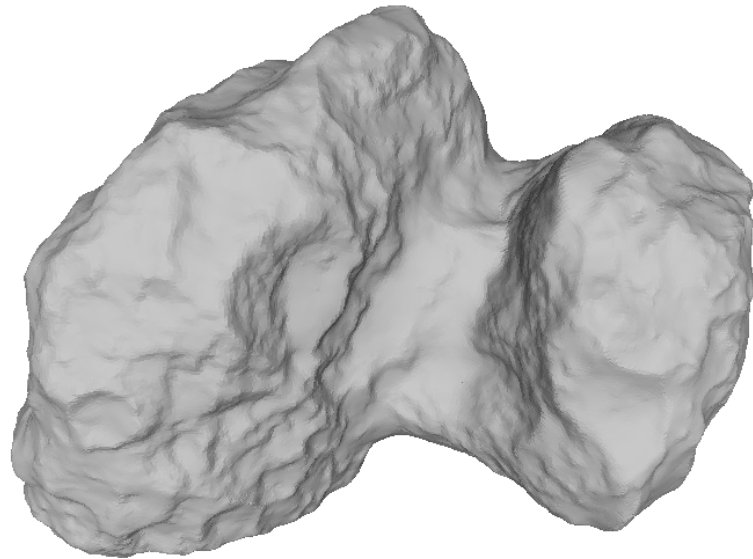
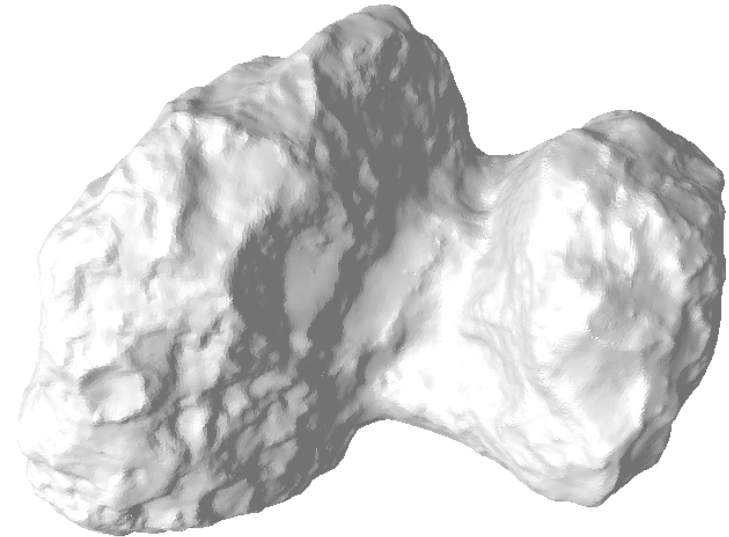


Image from data set



Rendered
Perspective projection
Distance 7.5 km
FOV 50°

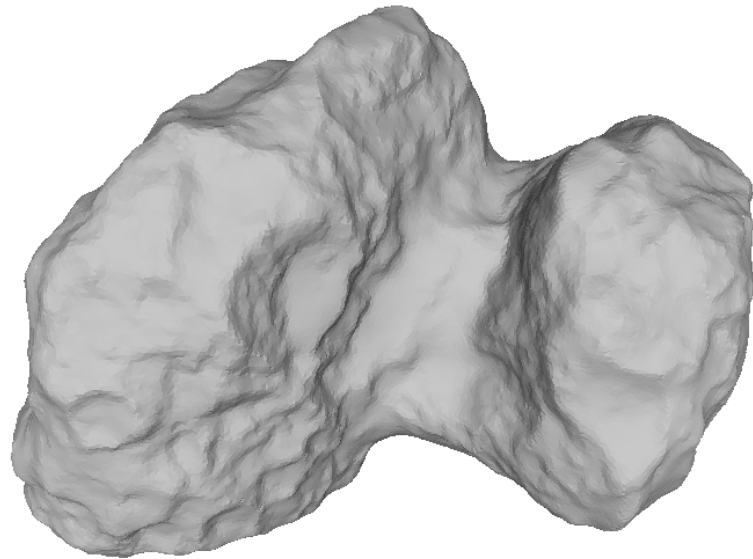
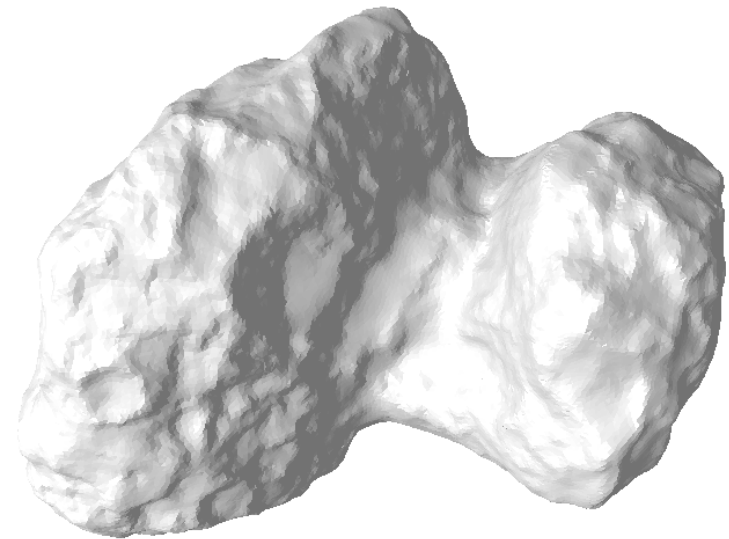


Image from data set



Rendered
Perspective projection
Distance 7.5 km
FOV 50°

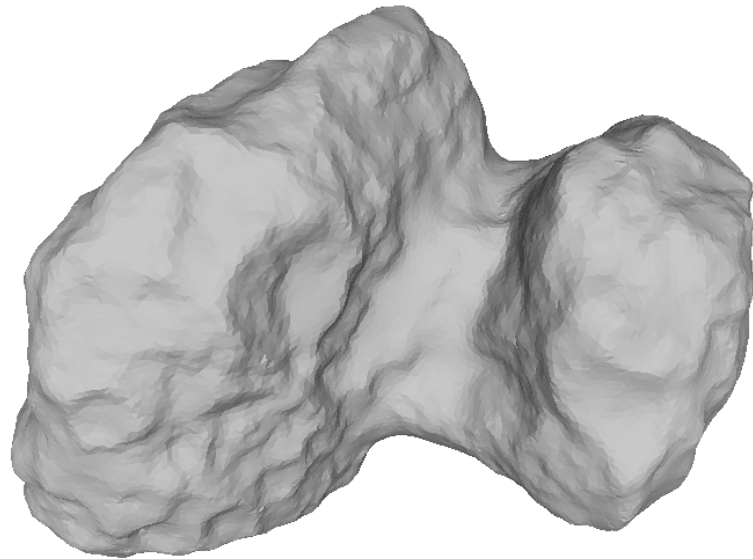
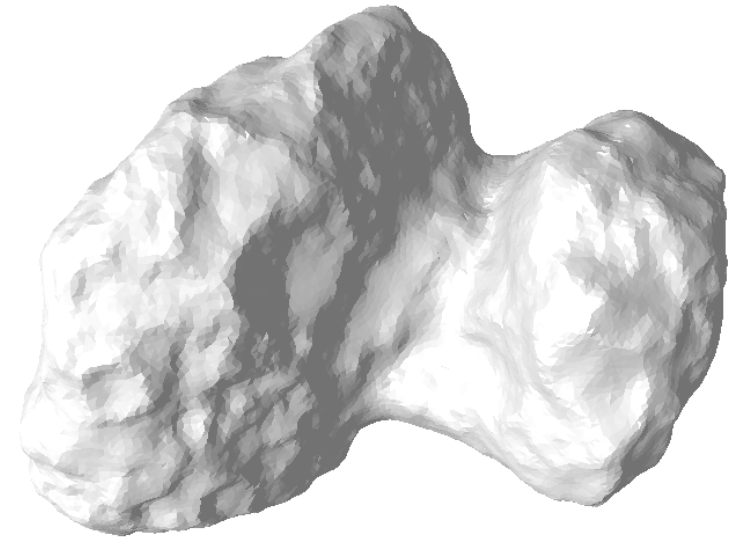


Image from data set



Rendered
Perspective projection
Distance 7.5 km
FOV 50°

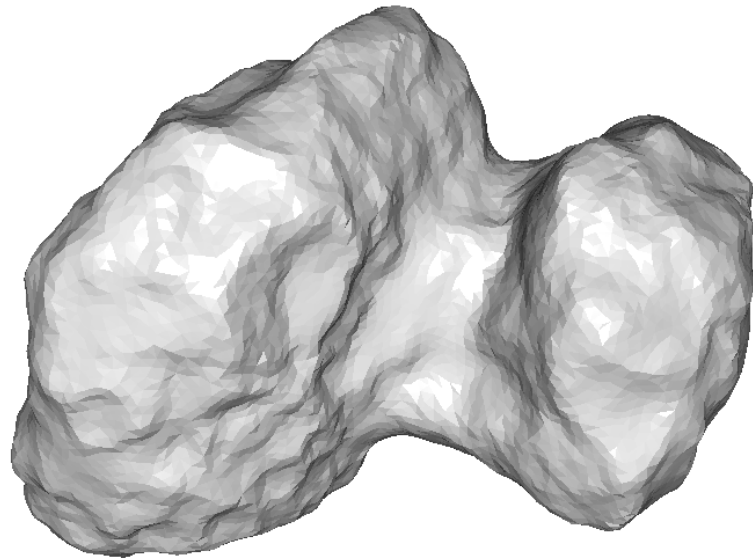
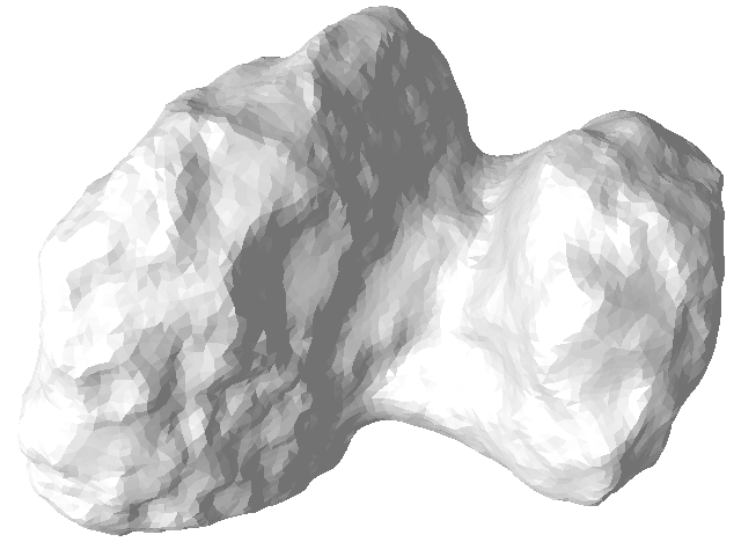


Image from data set



Rendered
Perspective projection
Distance 7.5 km
FOV 50°

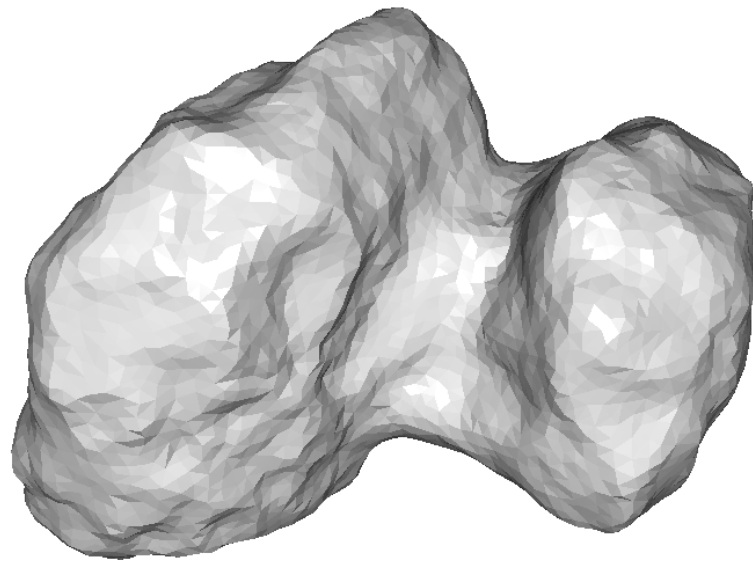
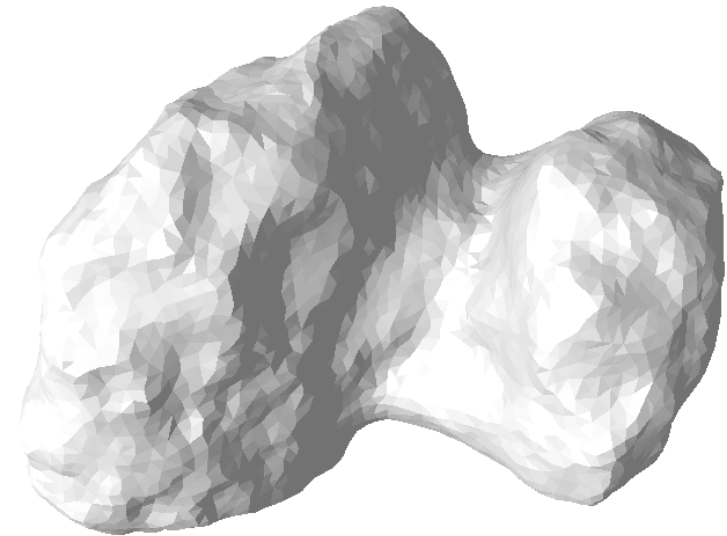


Image from data set



Rendered
Perspective projection
Distance 7.5 km
FOV 50°

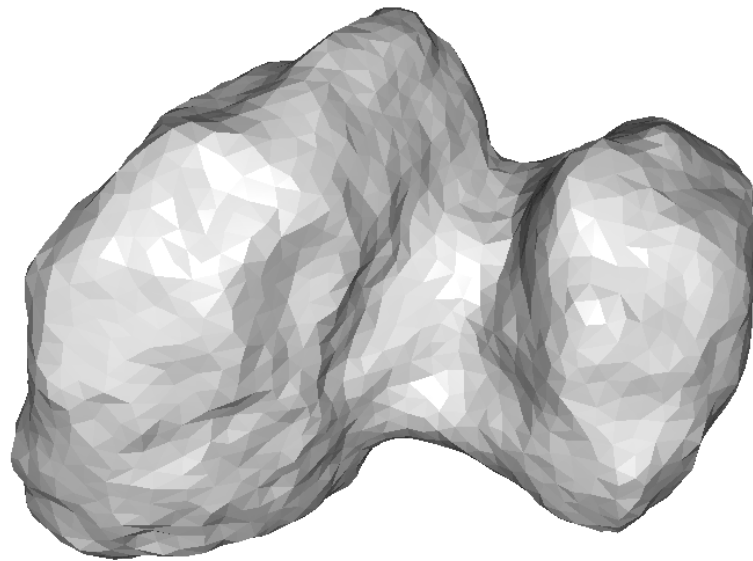
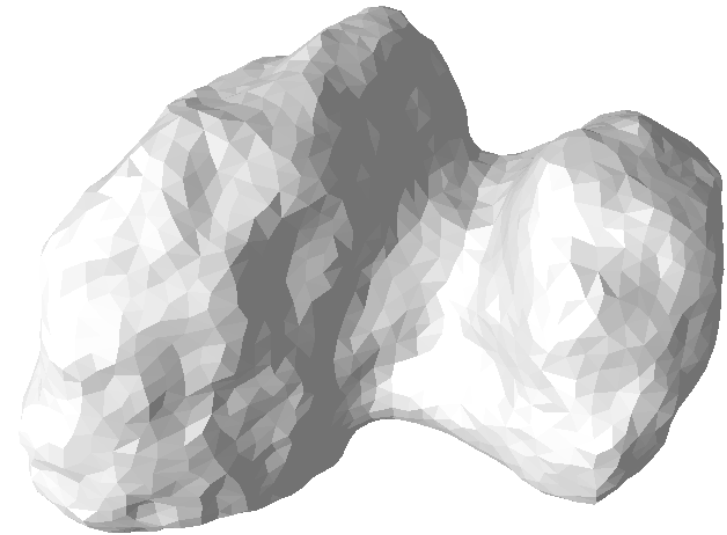


Image from data set



Rendered
Perspective projection
Distance 7.5 km
FOV 50°

→ The images are consistent with the plate shape models.

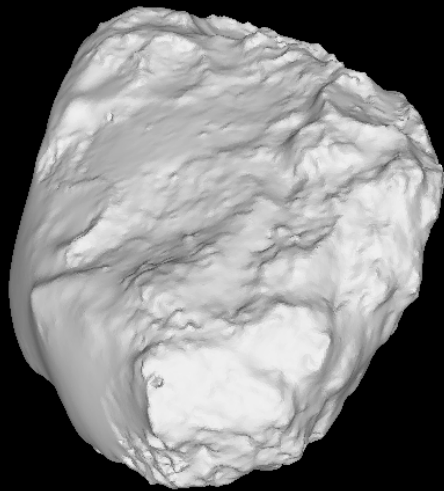
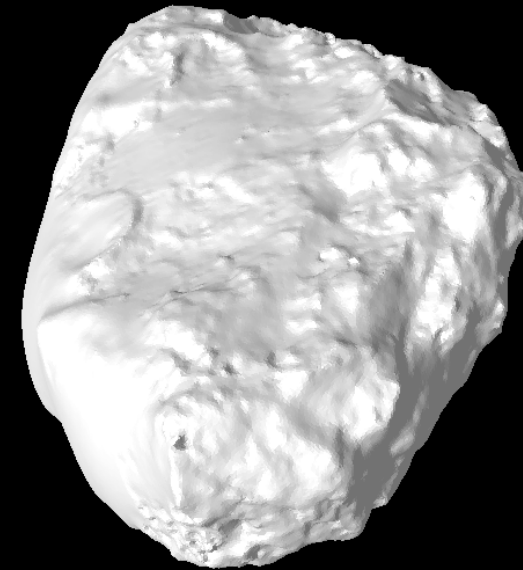


Image from data set



Rendered
Perspective projection
Distance 7.5 km
FOV 50°

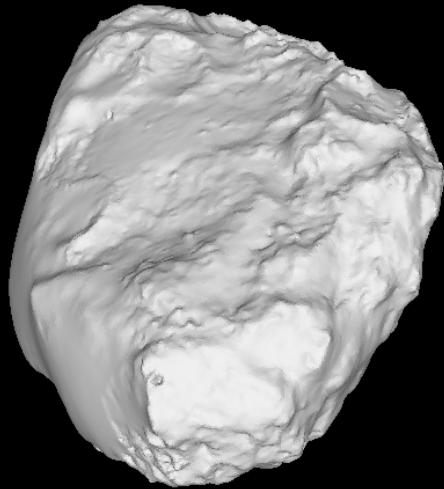
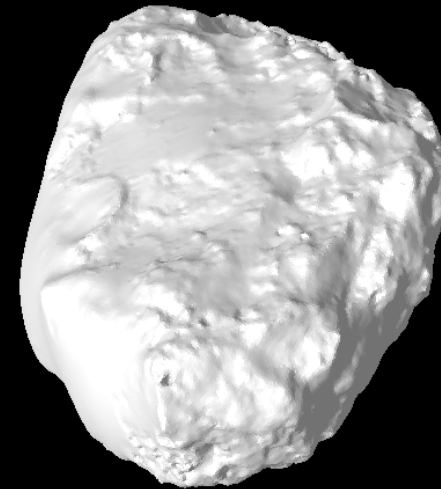


Image from data set



Rendered
Perspective projection
Distance 10 km
FOV 42.5°

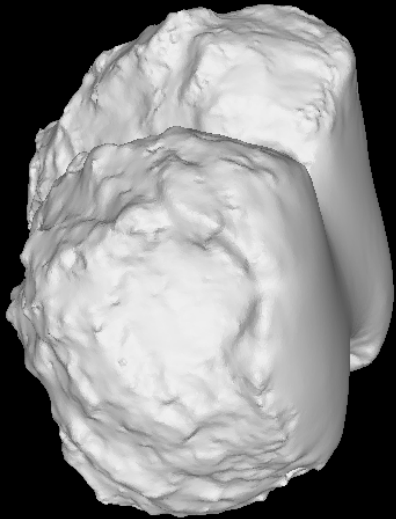


Image from data set



Rendered
Perspective projection
Distance 10 km
FOV 42.5°

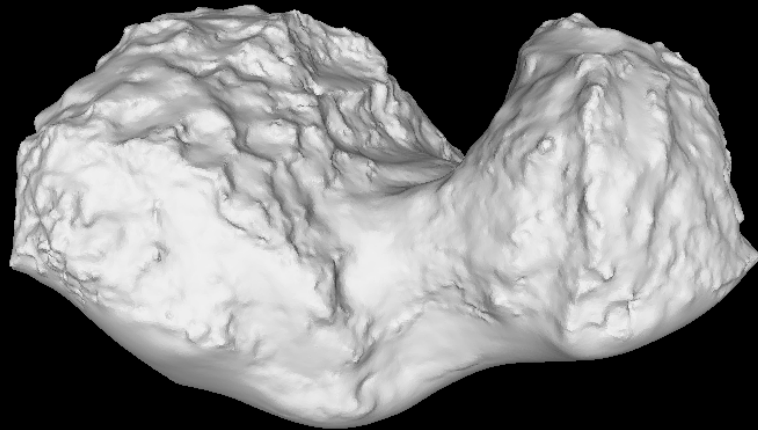
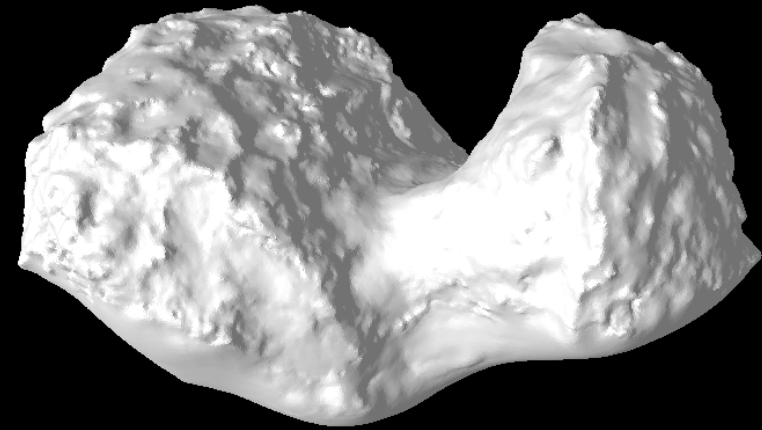


Image from data set



Rendered
Perspective projection
Distance 10 km
FOV 40°

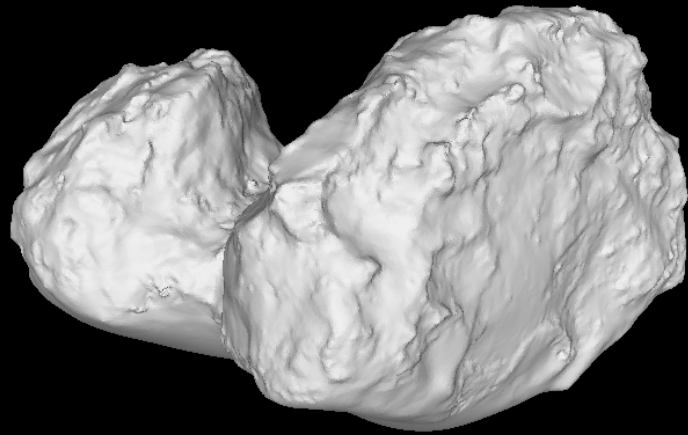
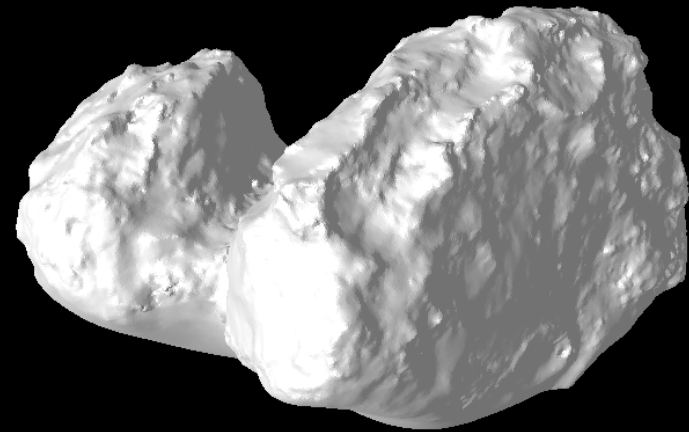


Image from data set



Rendered
Perspective projection
Distance 10 km
FOV 40°

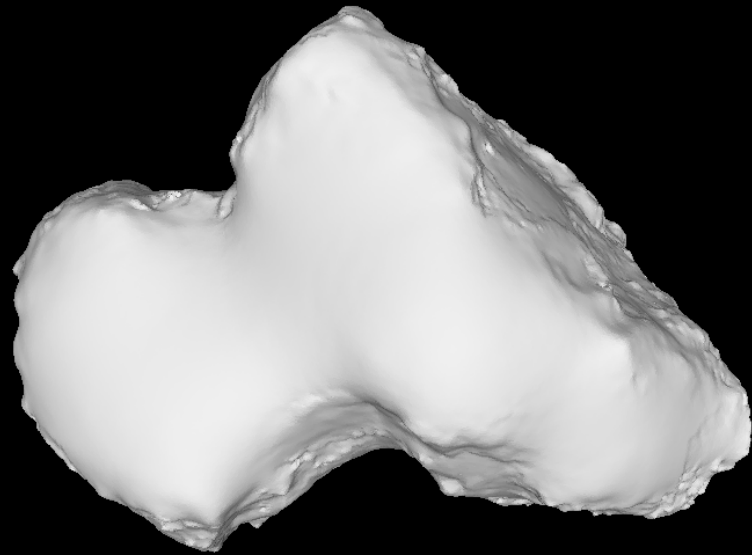


Image from data set



Rendered
Perspective projection
Distance 10 km
FOV 40°

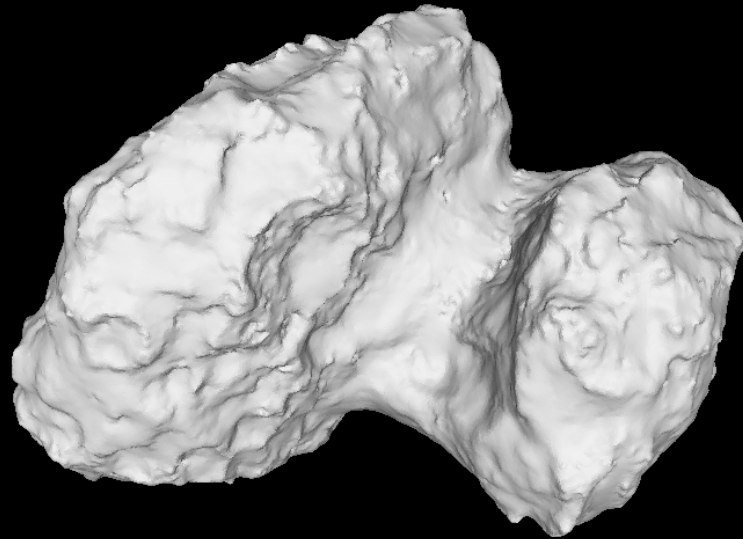
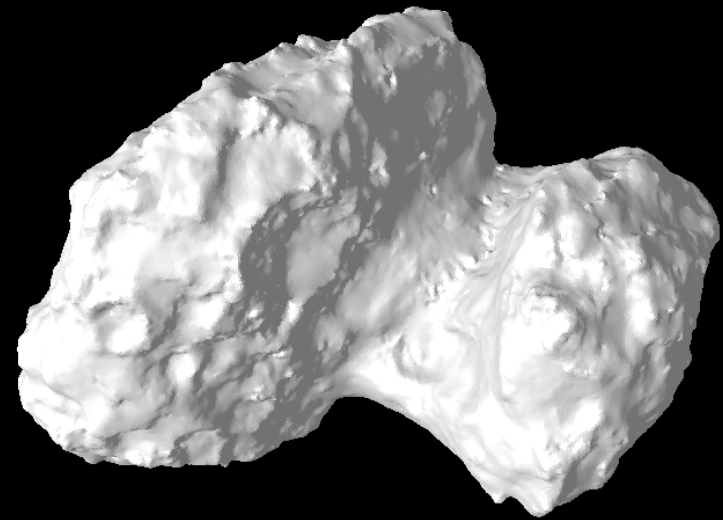


Image from data set



Rendered
Perspective projection
Distance 10 km
FOV 40°

→ The images are consistent with the plate shape models.

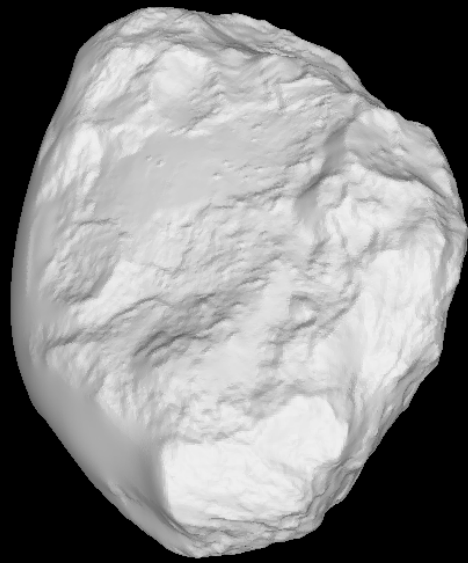
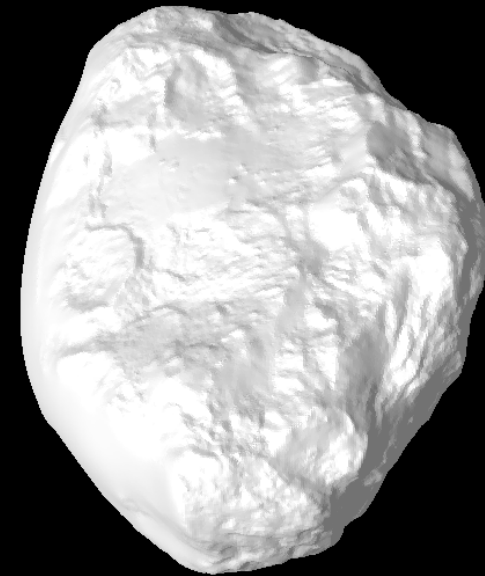


Image from data set



Rendered
Perspective projection
Distance 10 km
FOV 40°

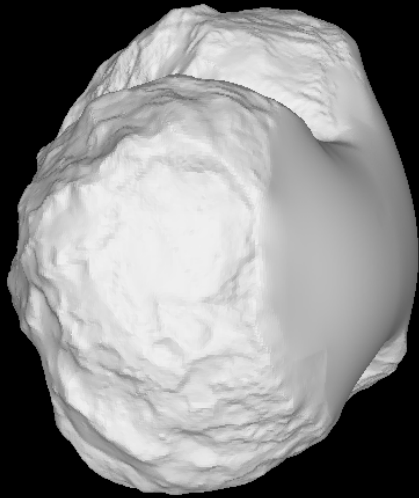
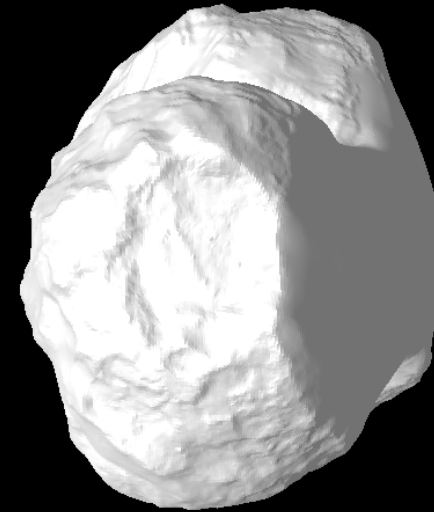


Image from data set



Rendered
Perspective projection
Distance 10 km
FOV 40°

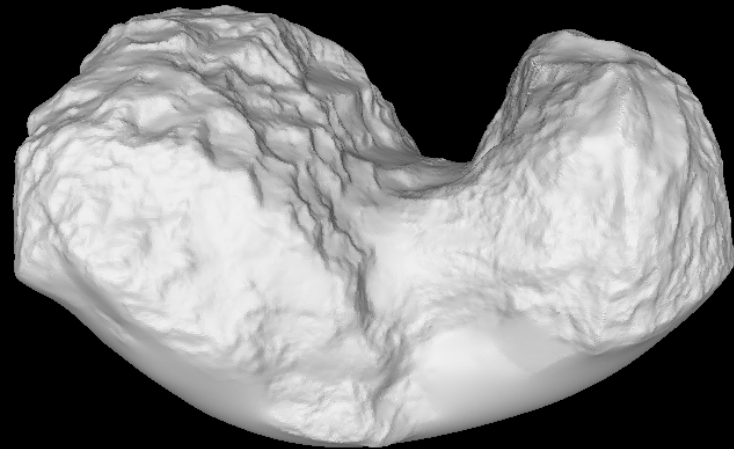
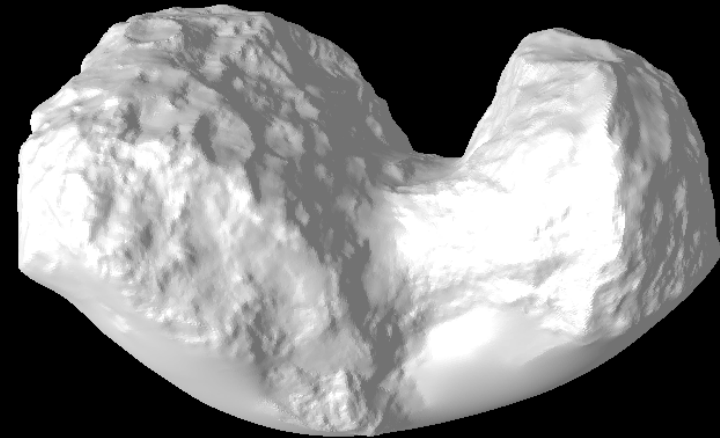


Image from data set



Rendered
Perspective projection
Distance 10 km
FOV 40°

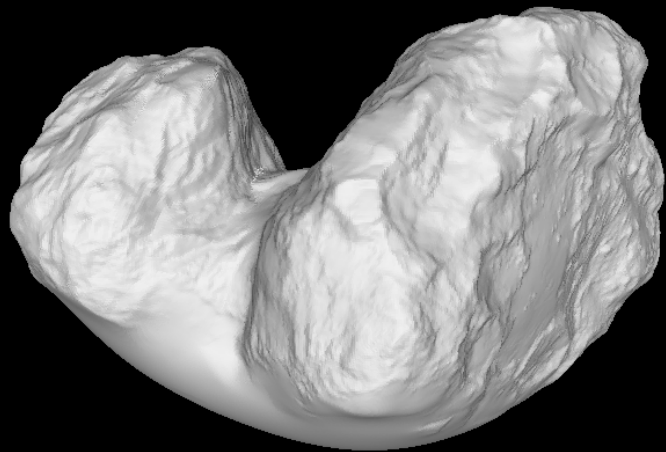
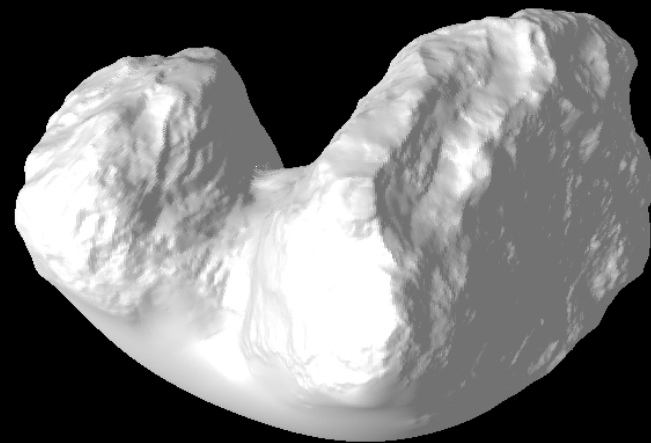


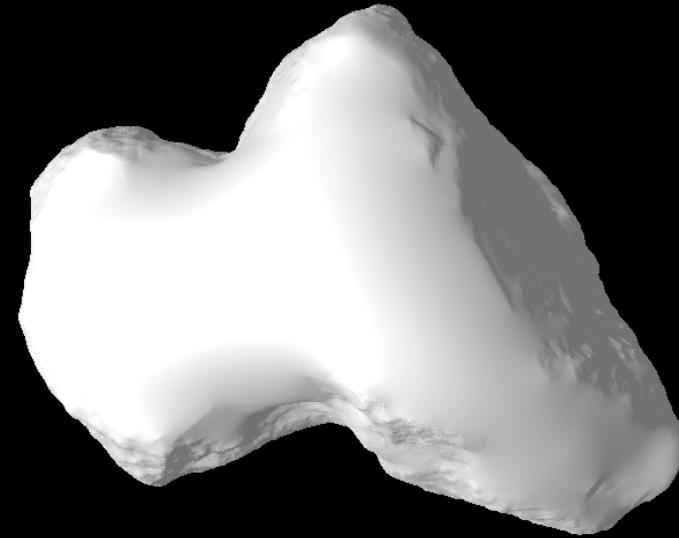
Image from data set



Rendered
Perspective projection
Distance 10 km
FOV 40°



Image from data set



Rendered
Perspective projection
Distance 10 km
FOV 40°

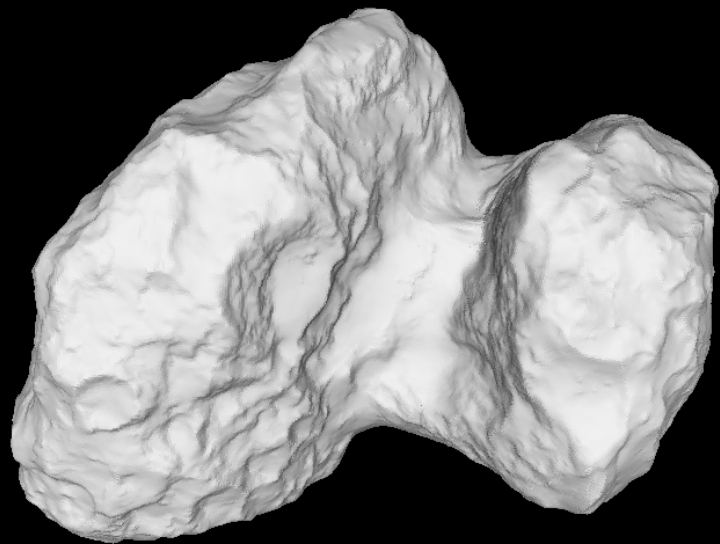
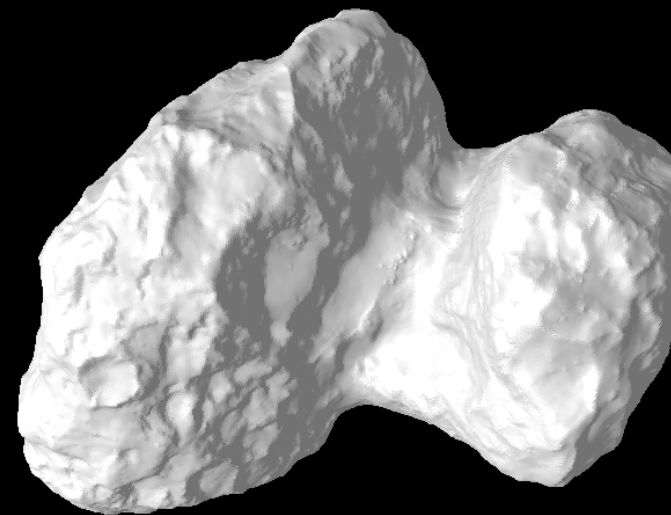


Image from data set

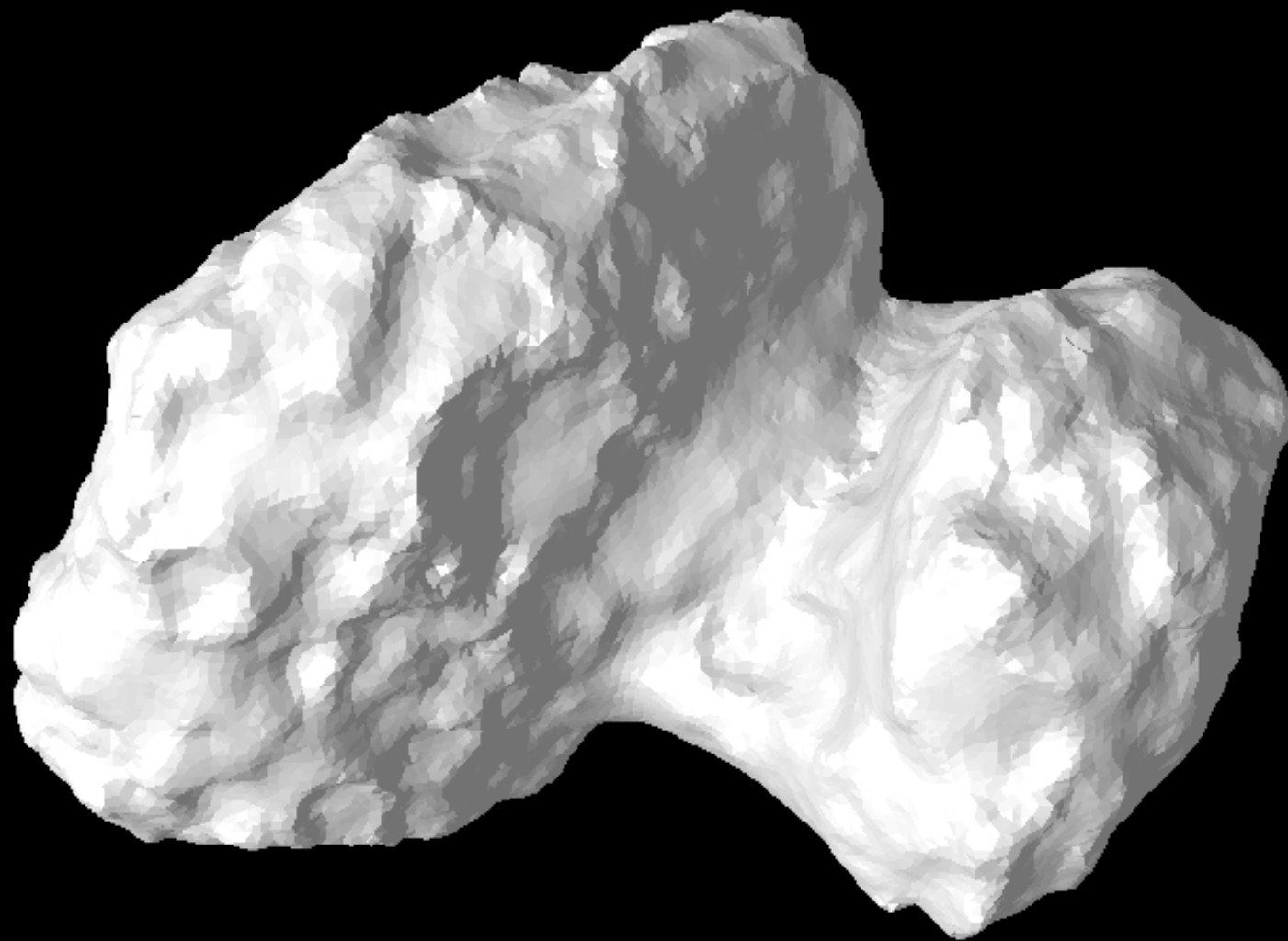


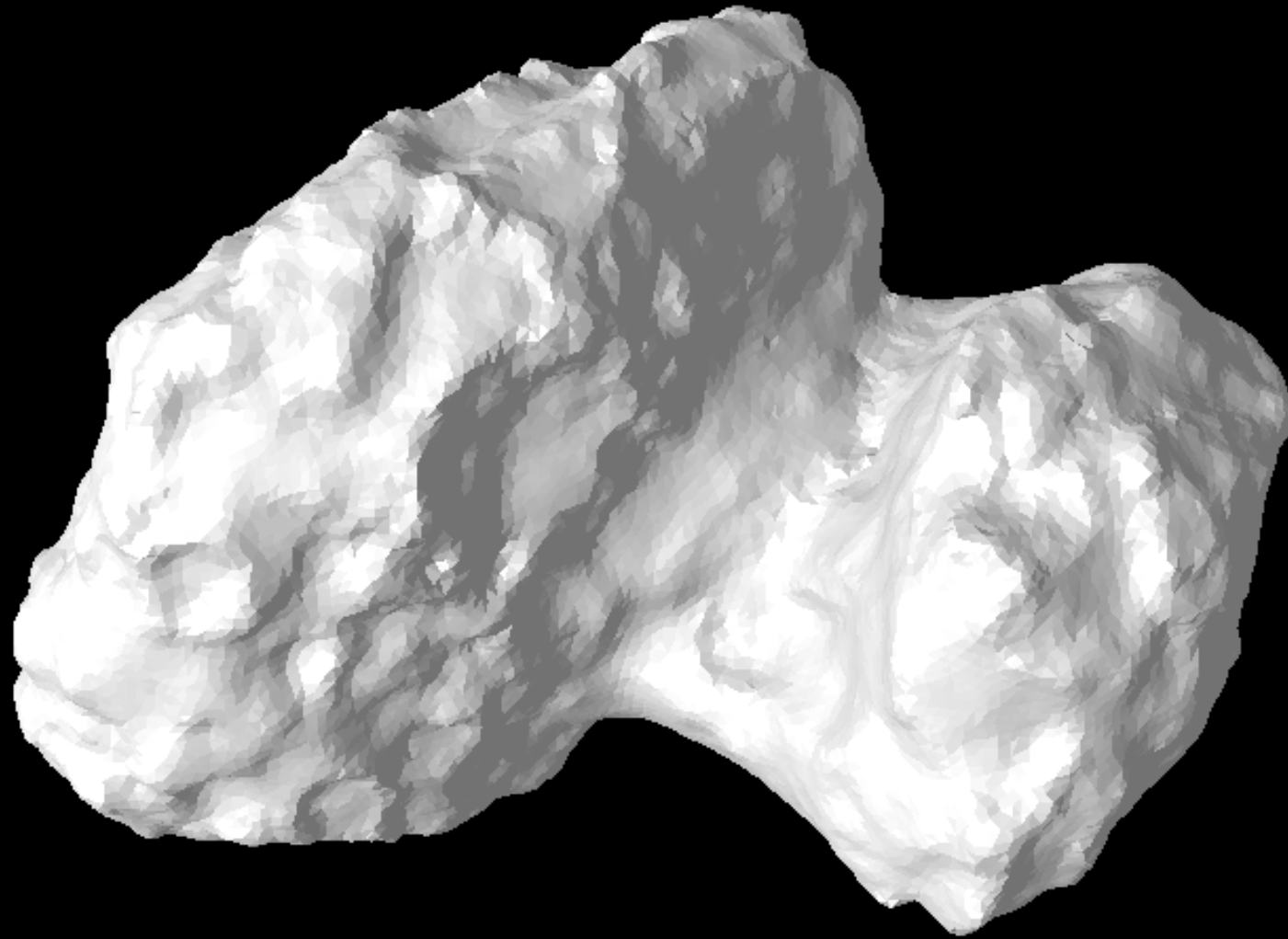
Rendered
Perspective projection
Distance 10 km
FOV 40°

→ The images are consistent with the plate shape models.

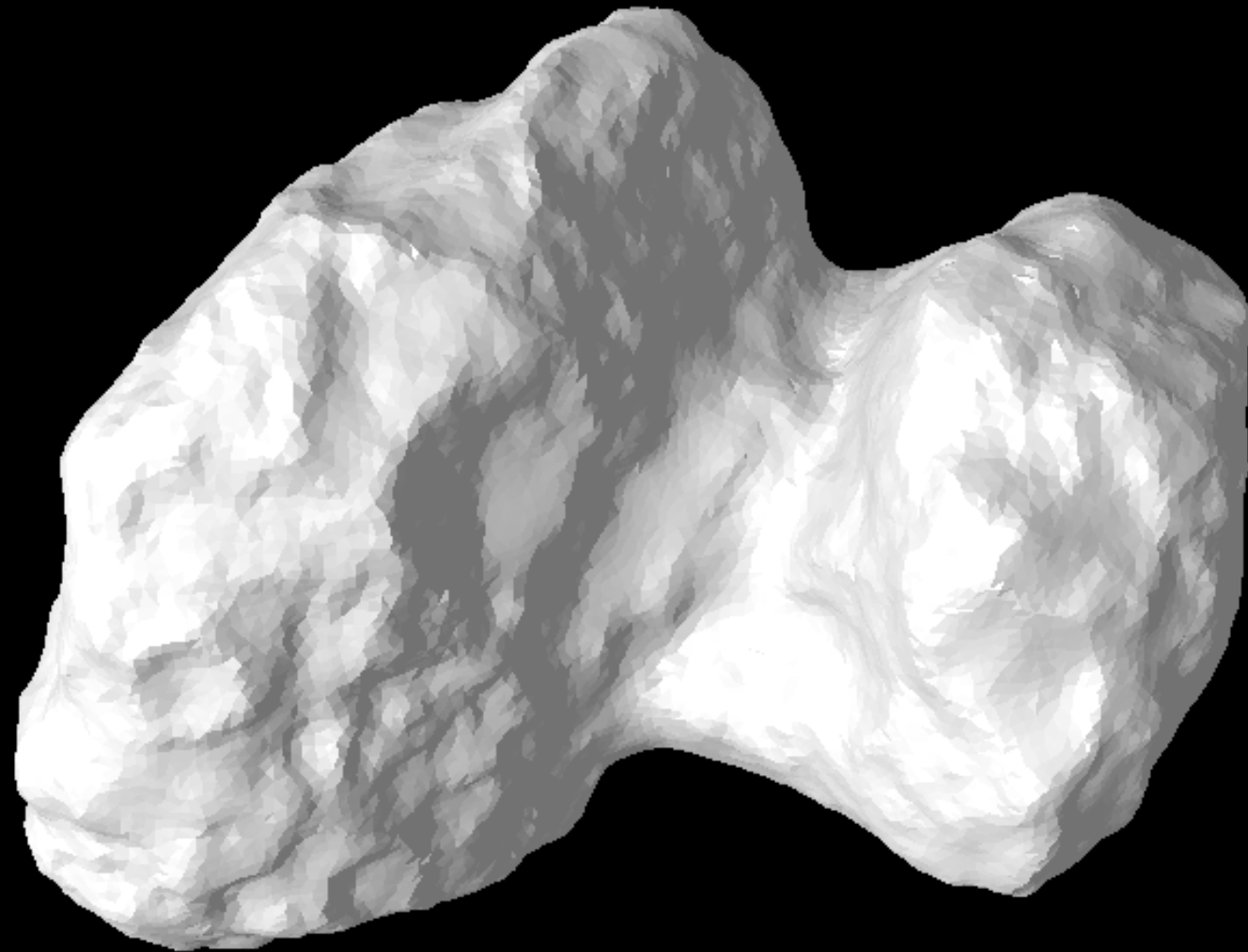
3

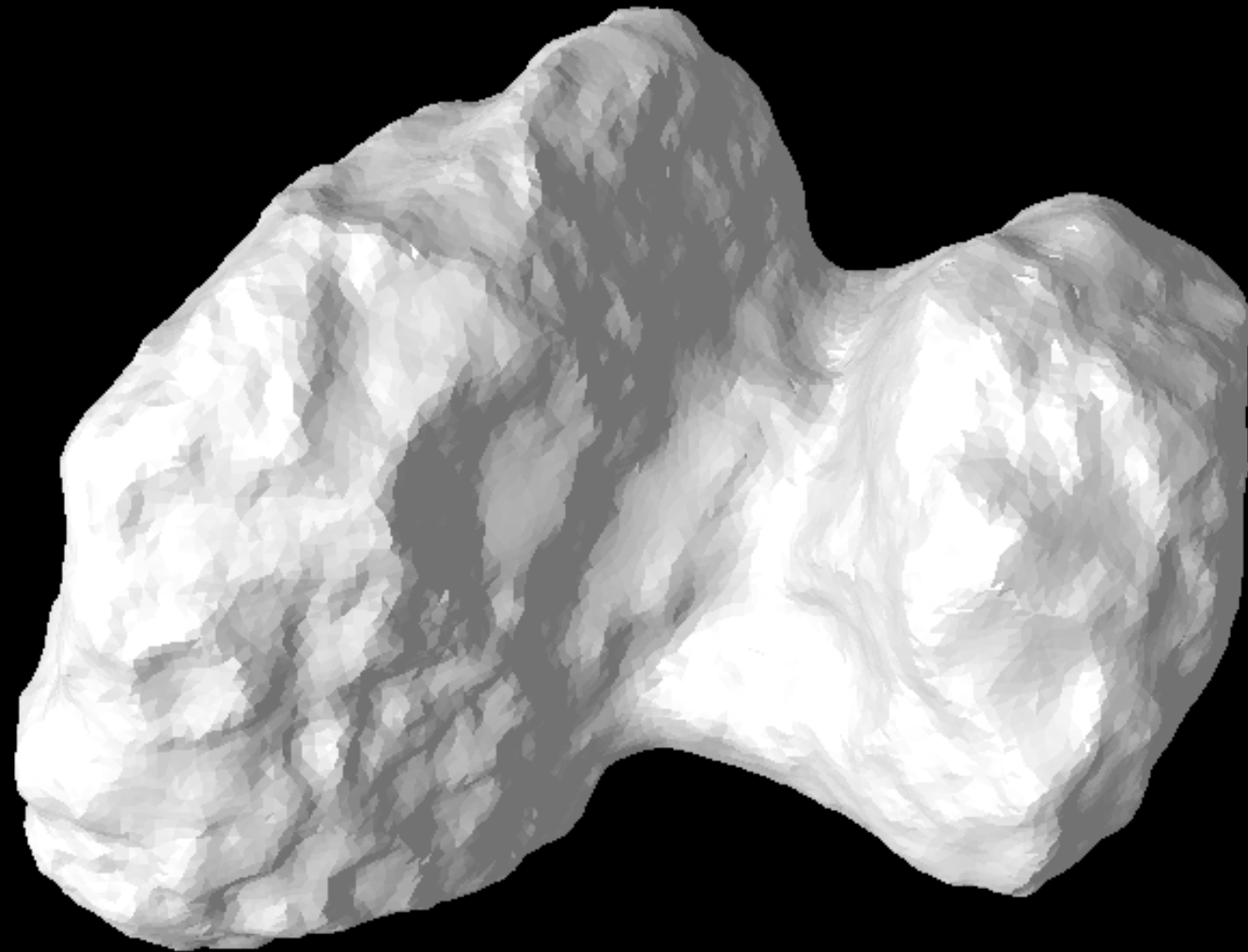
Consistency between plate shape models and DSKs





→ The DSKs are consistent with the plate shape models (point check).

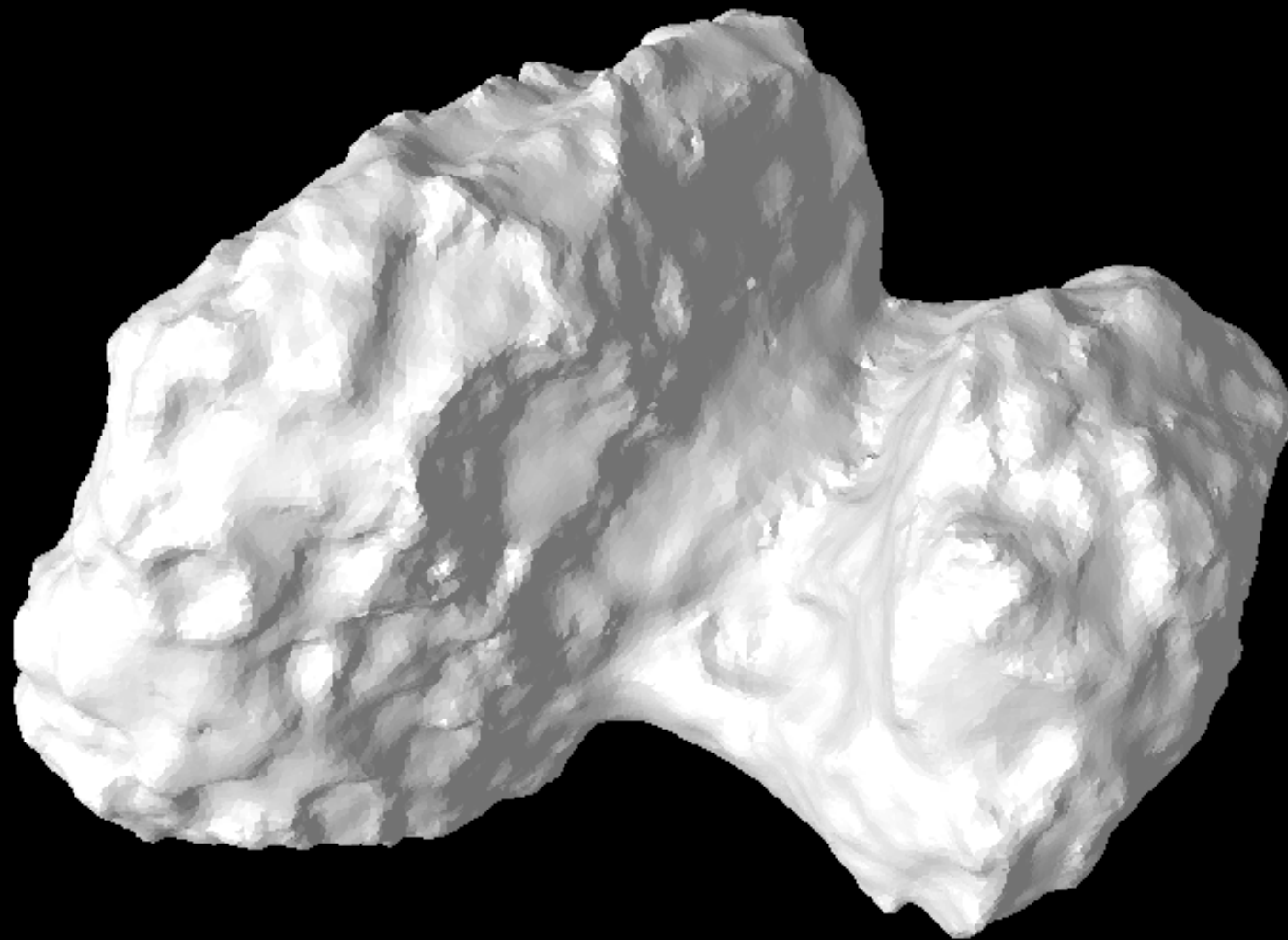


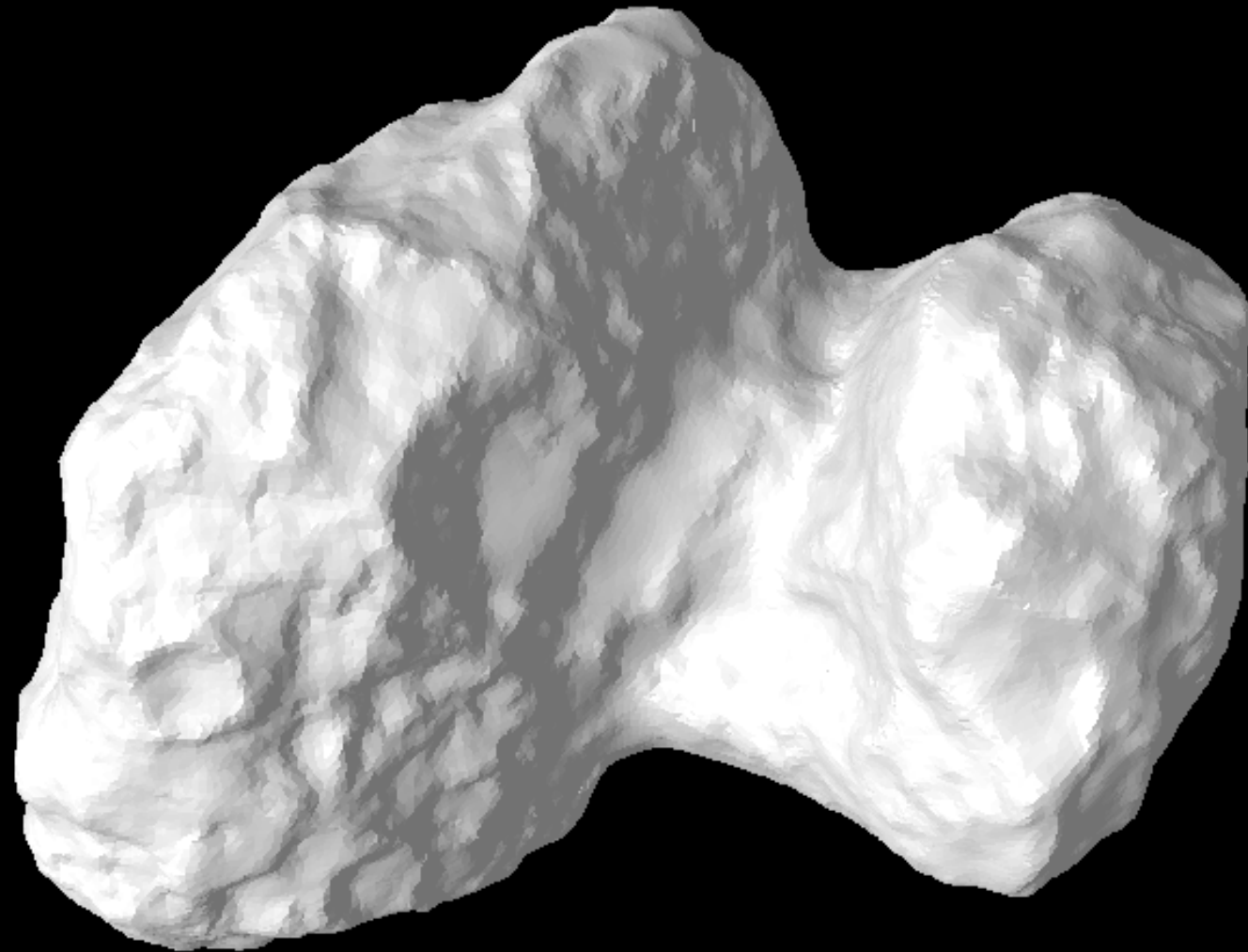


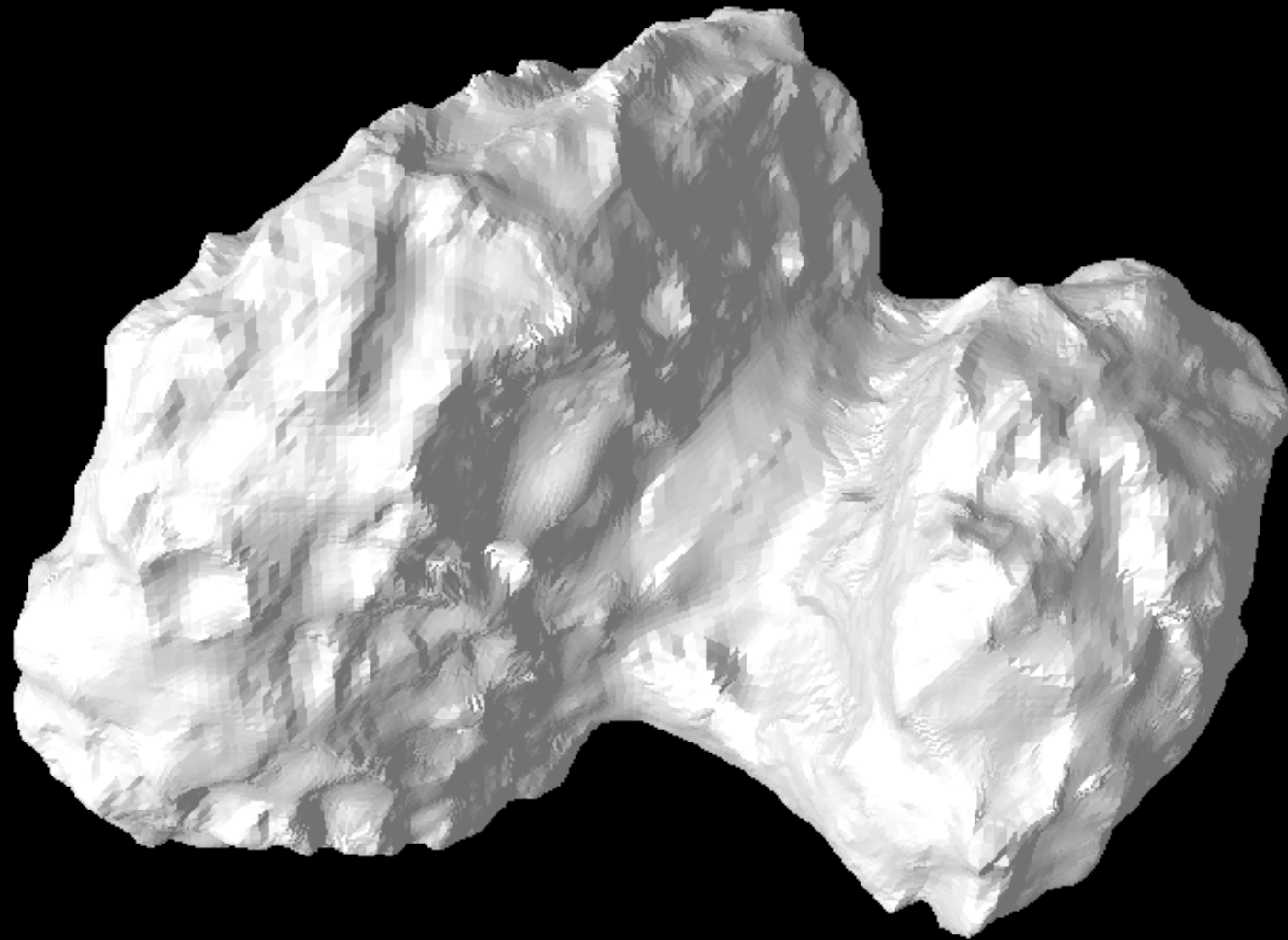
→ The DSKs are consistent with the plate shape models (point check).

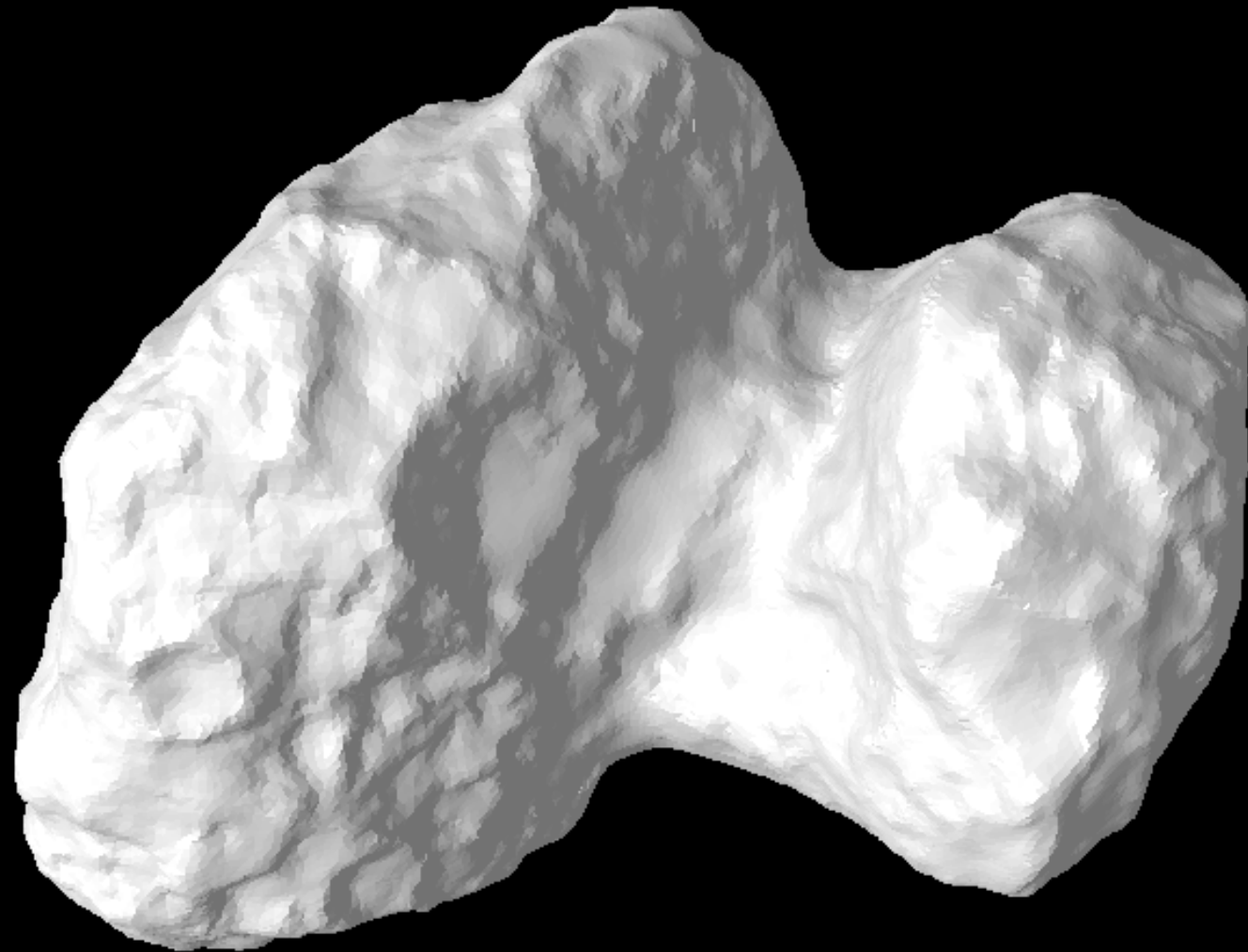
4

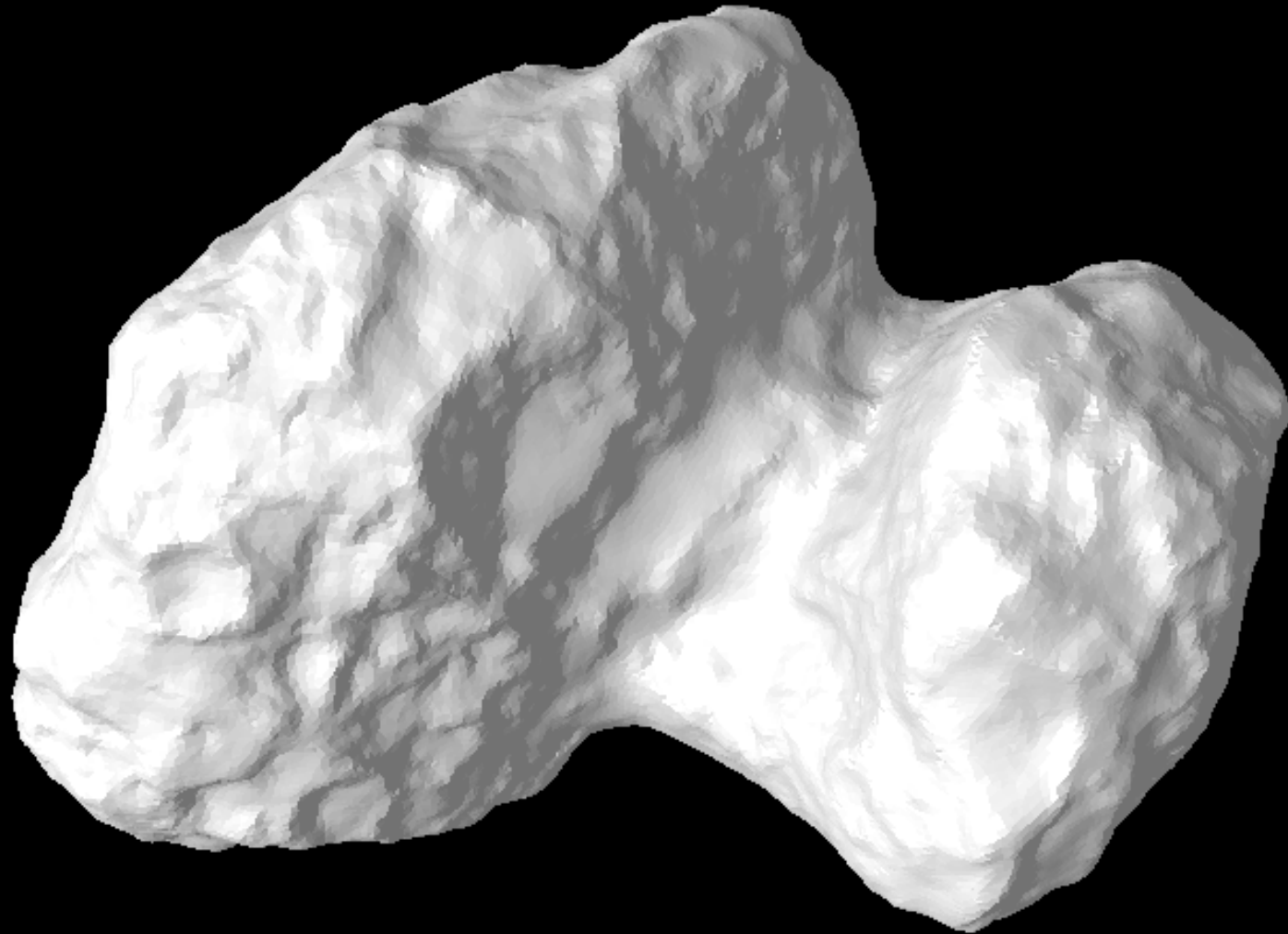
Consistency between the
shape models from the two
techniques and the MOC
shape model



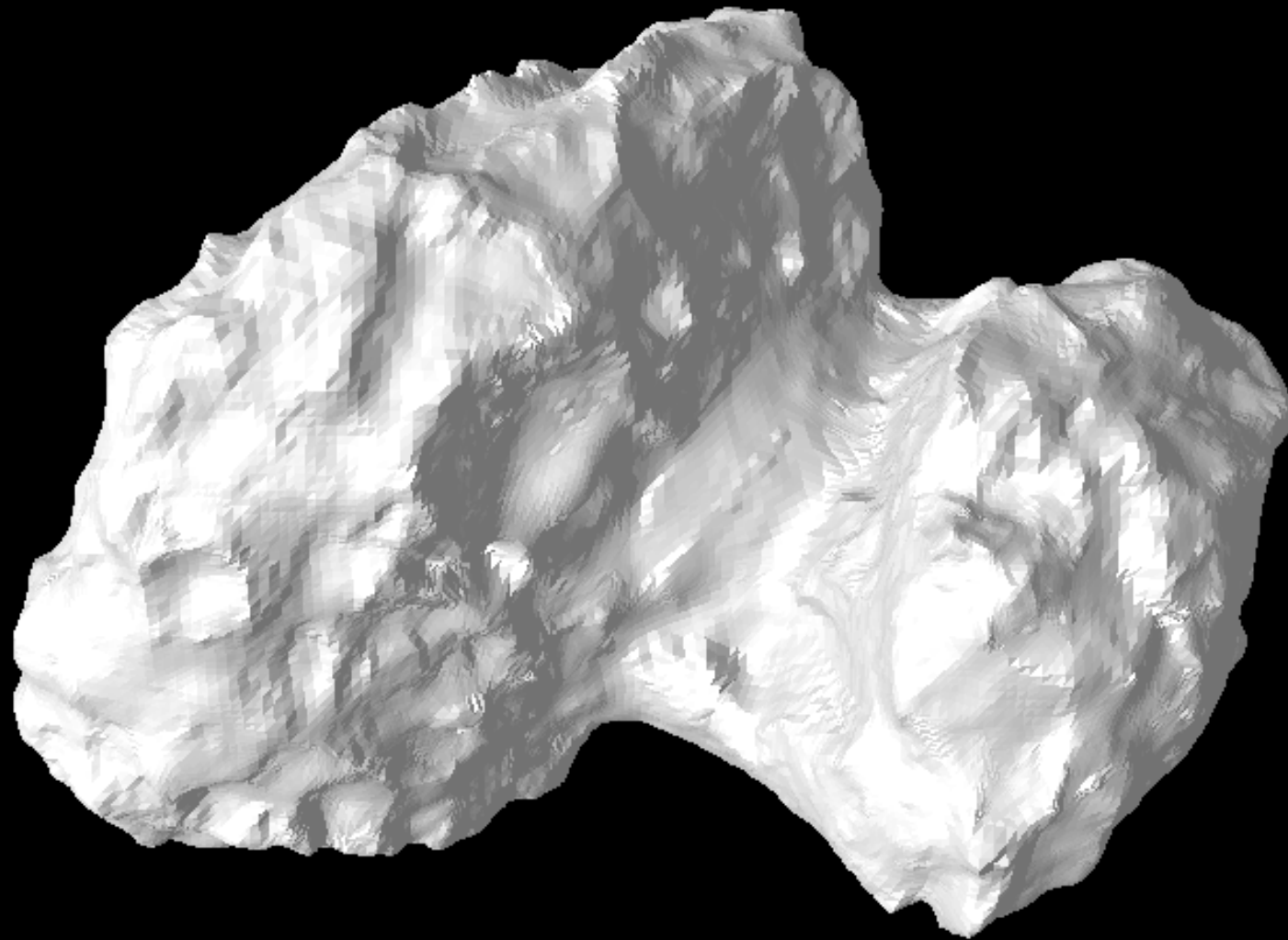


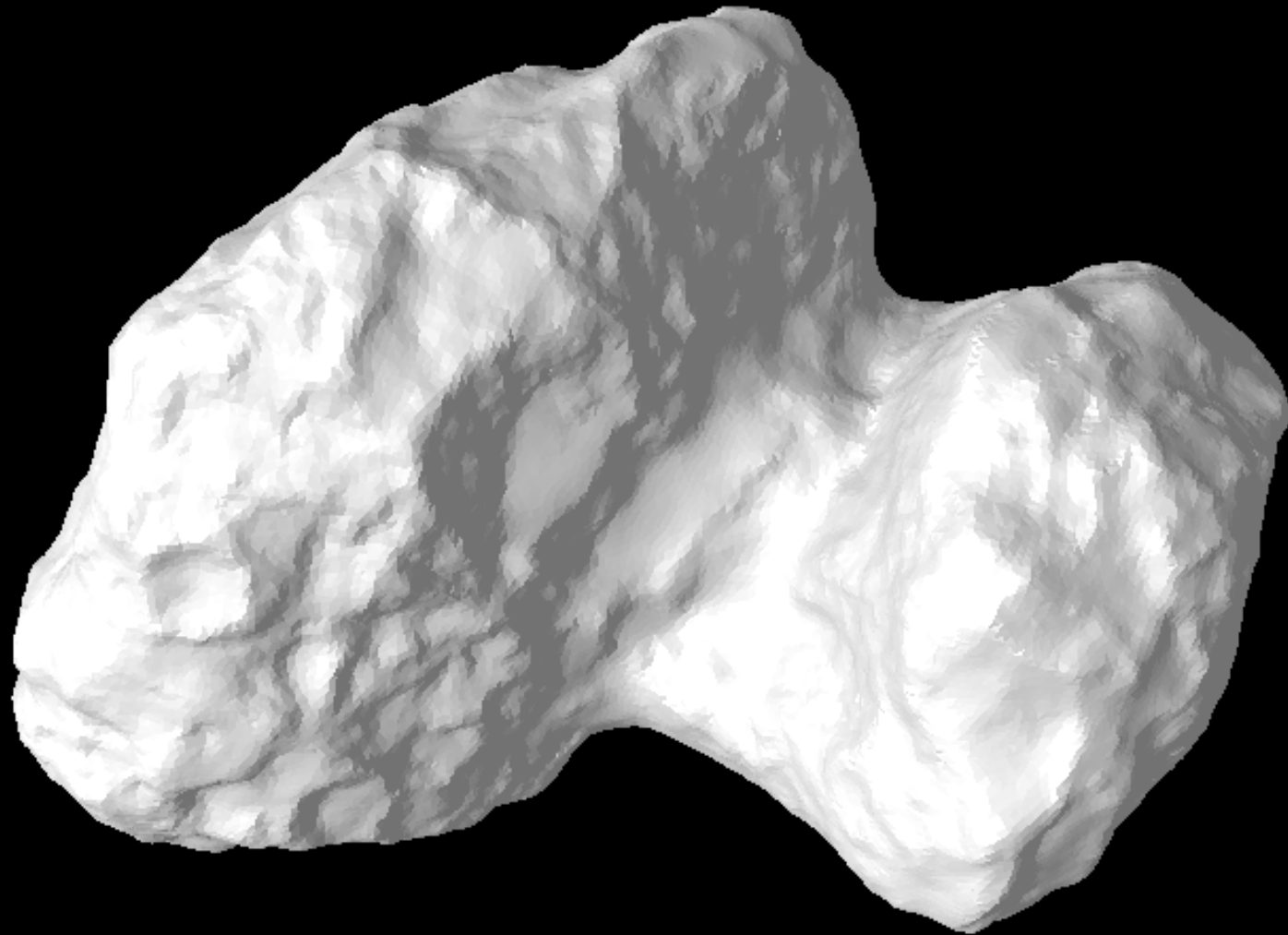




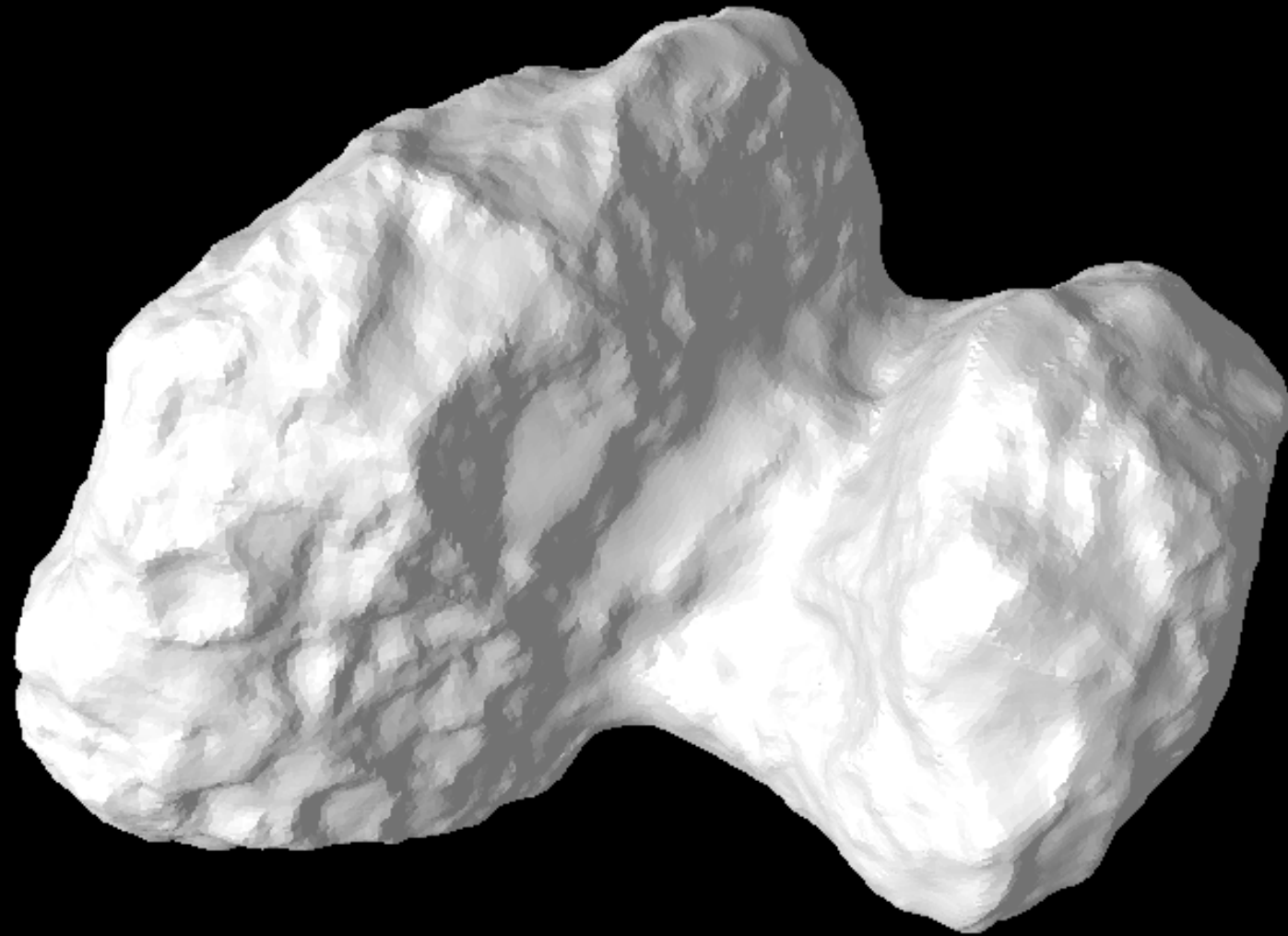


Rotated by 10°

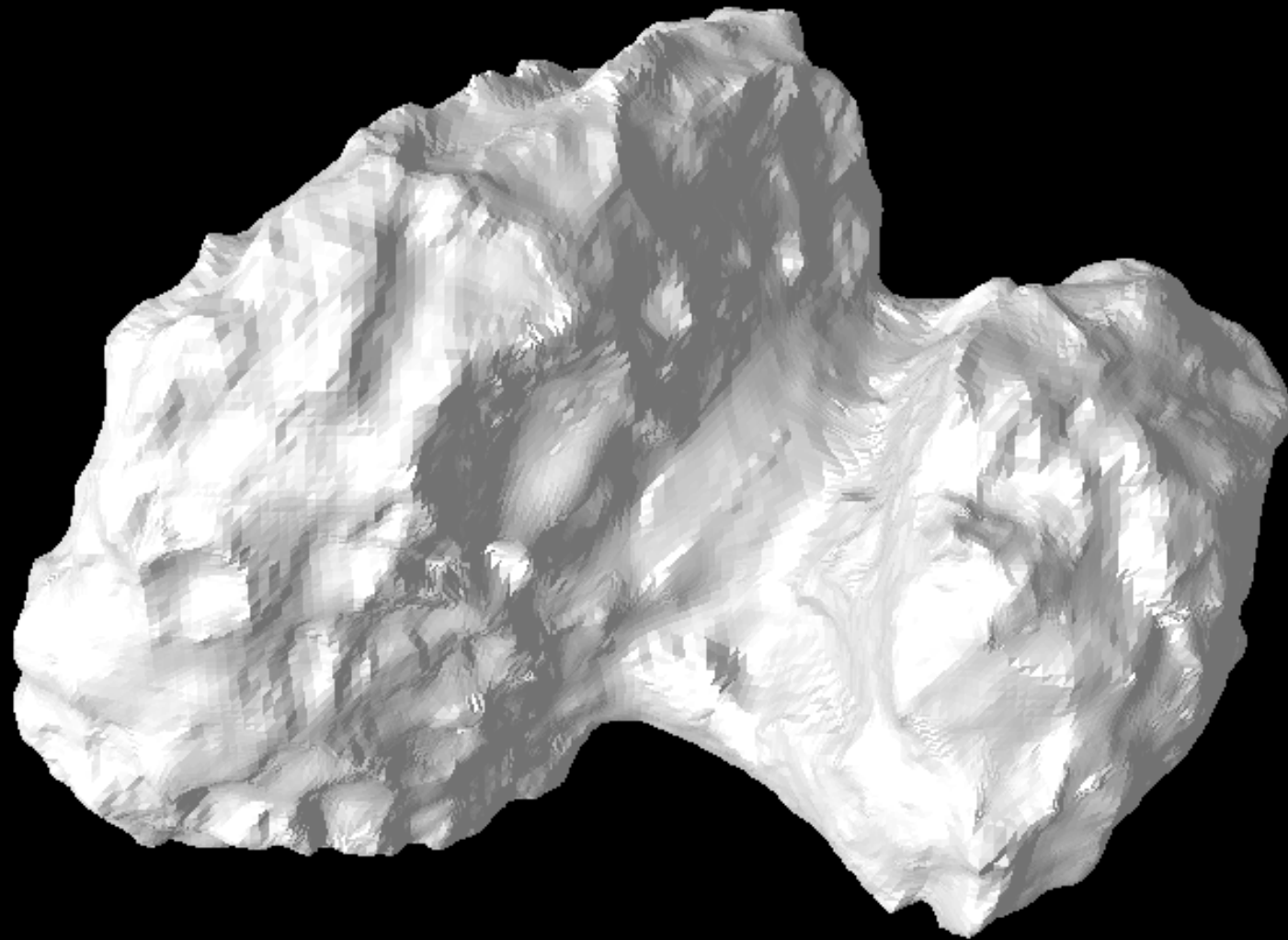




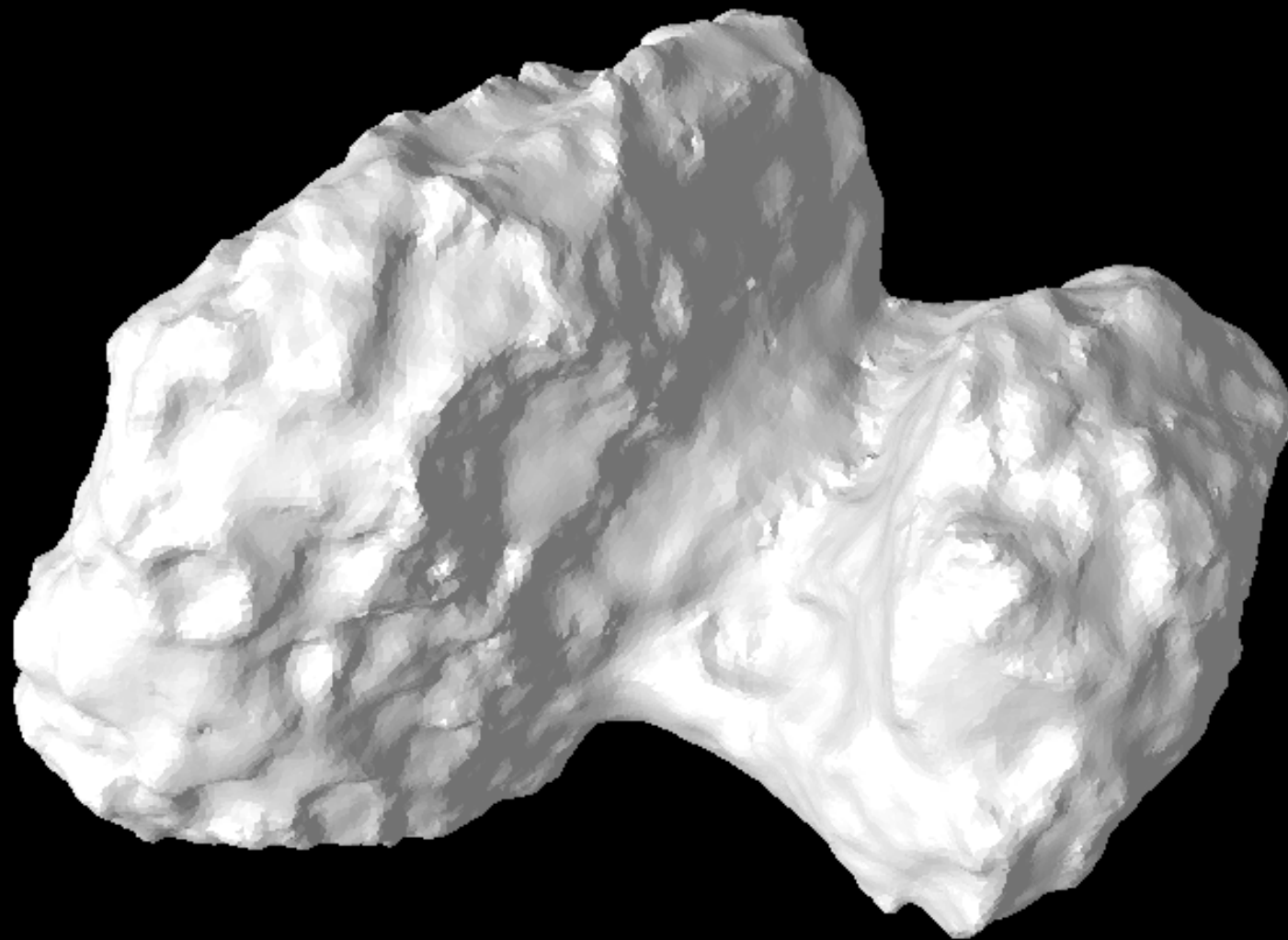
Rotated by 10°

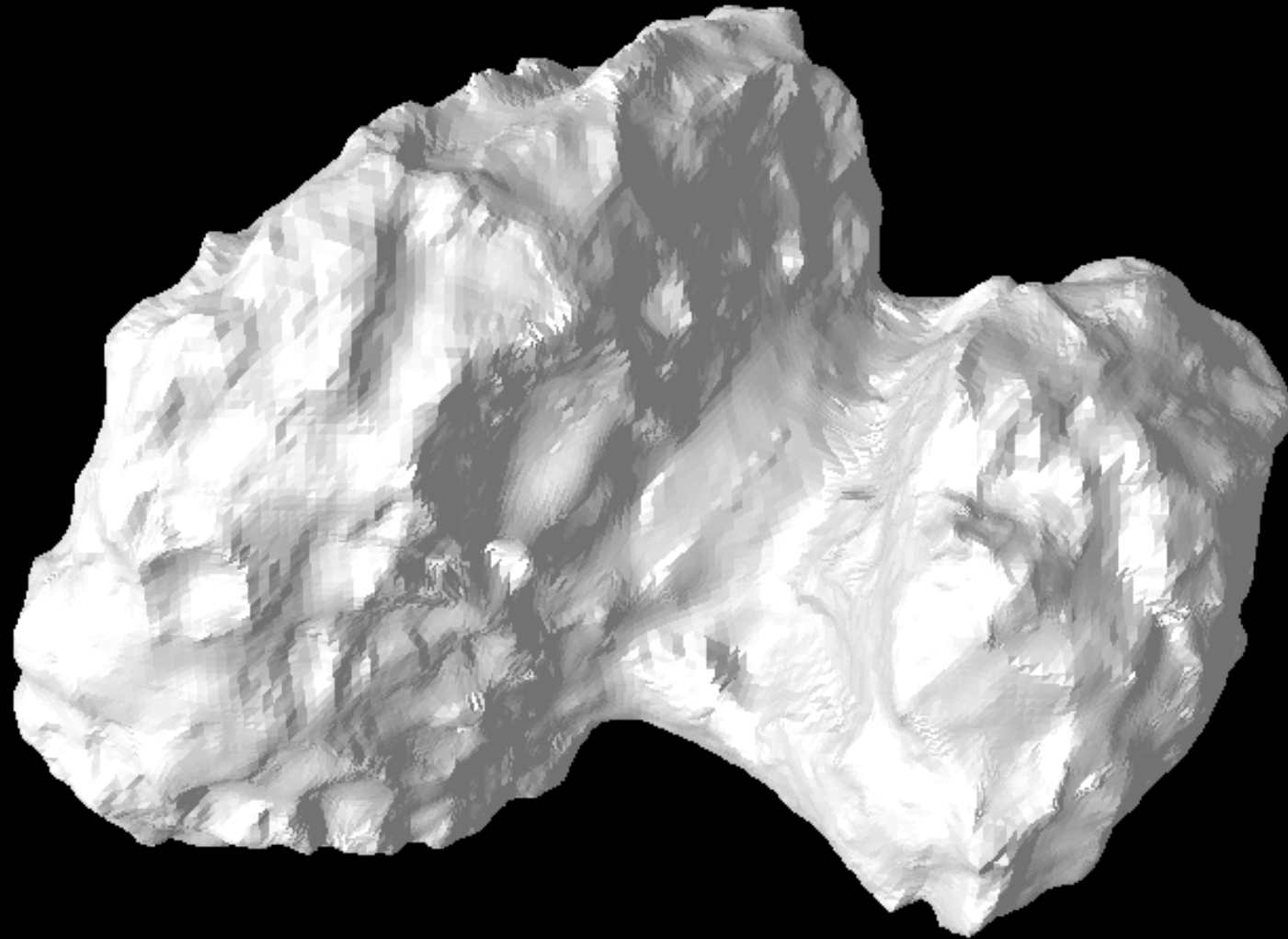


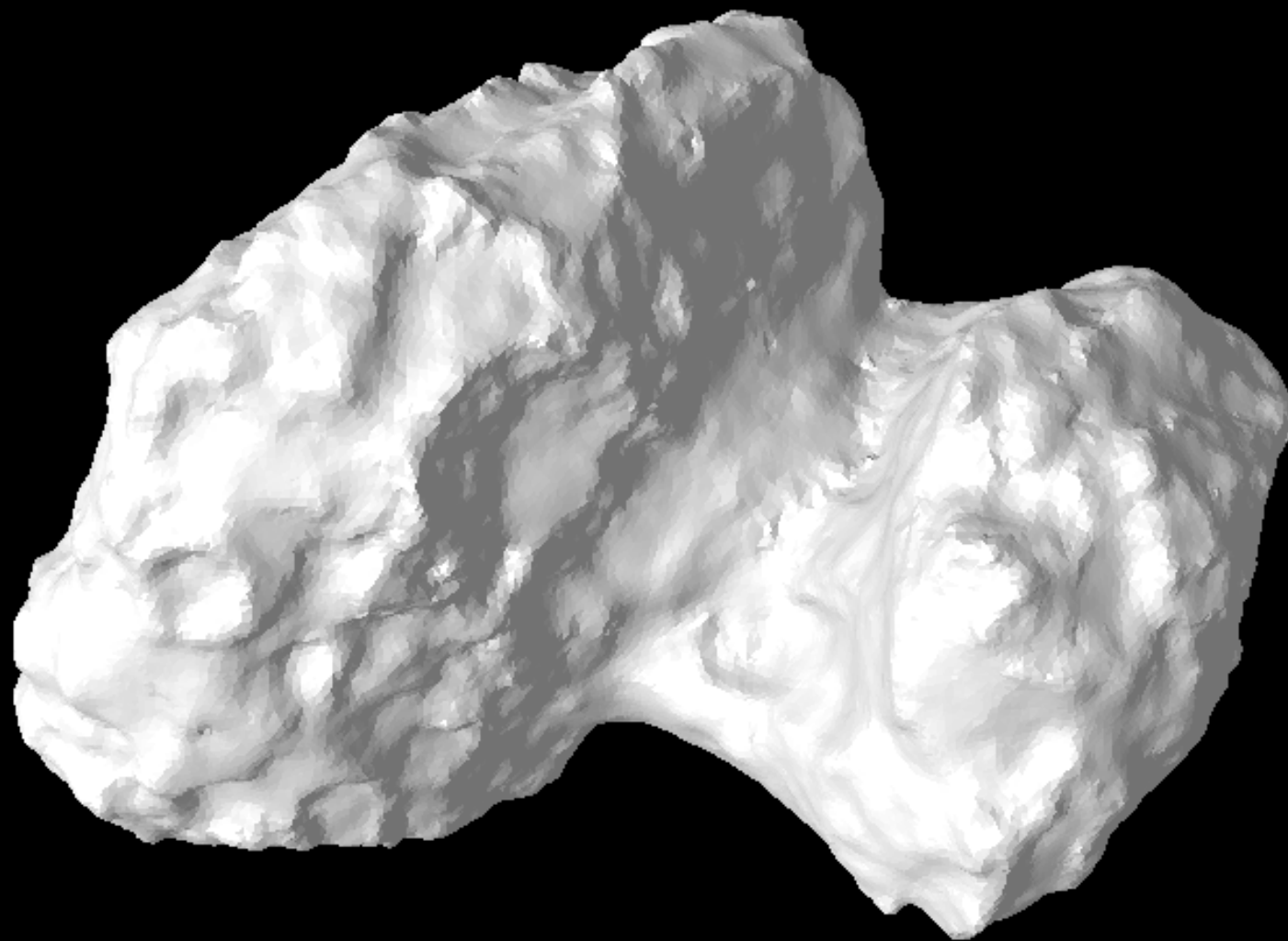
Rotated by 10° and translated by -200 m in x and -150 m in y

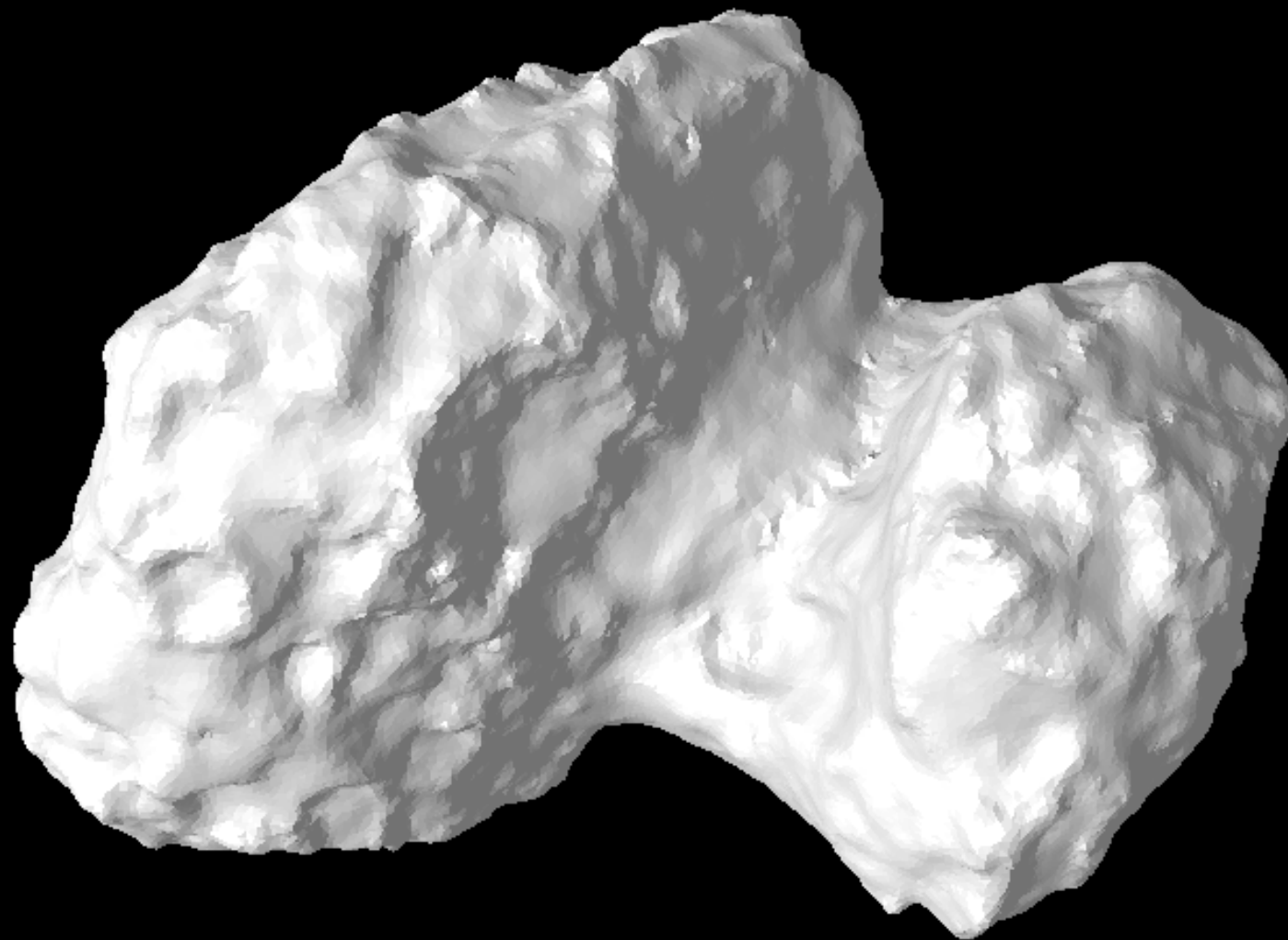


→ The frame used for the shape model is off from the MOC frame (to which the Cheops frame is equivalent by definition) by 10° rotation and 250 m translation.

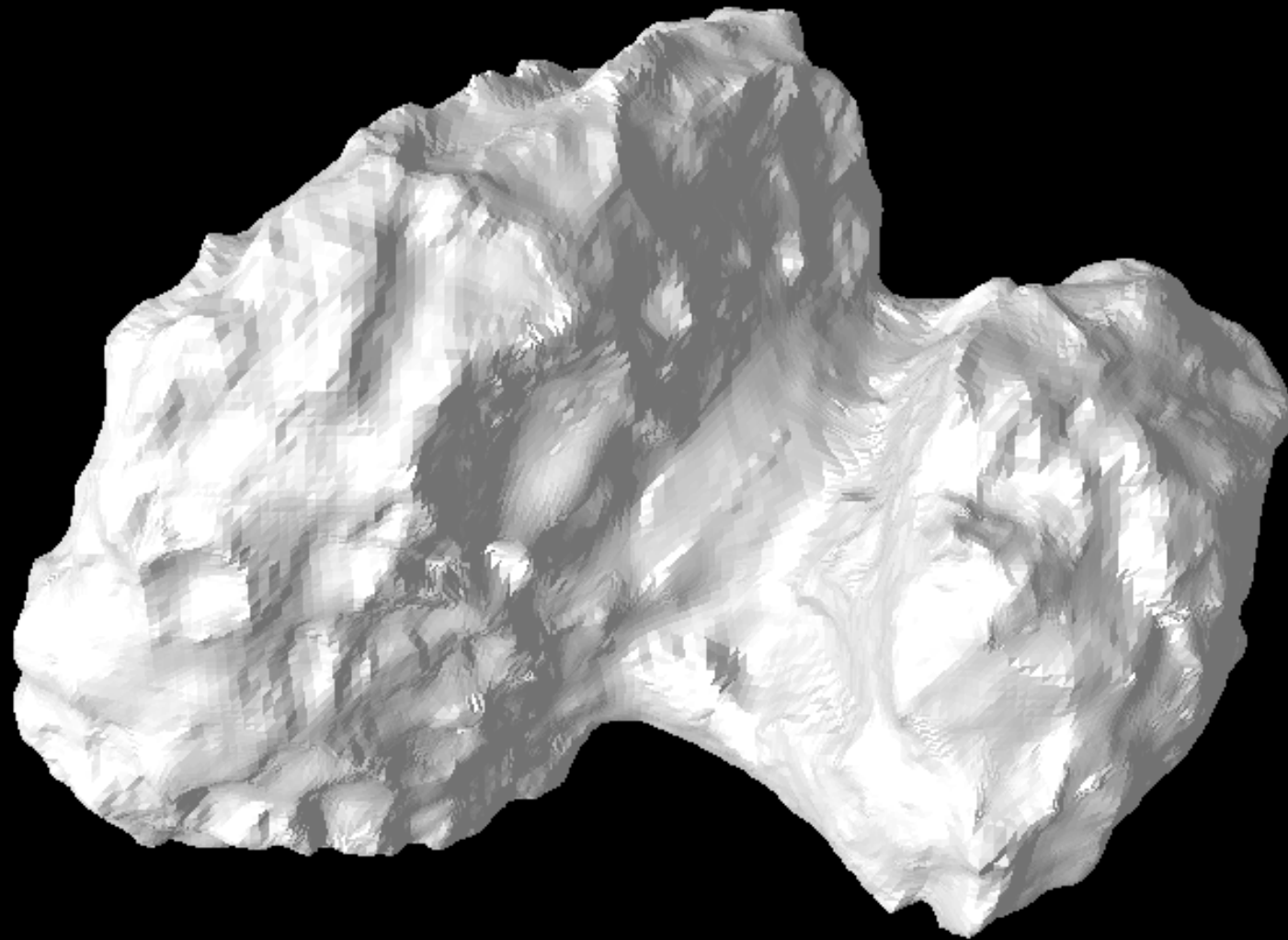








Rotated by 0.5° around x -, y -, and z -axis



→ The frame used for the shape model is off from the MOC frame (to which the Cheops frame is equivalent by definition) by $\sim 1^\circ$ rotation

Because the shape models from both techniques are not provided in the Cheops frame, a quantitative analysis of the shapes themselves is pending.

5

Efficiency of the DSKs

Computation times for one million intersections

# plates	DSK created by			
	MSPCD	SPC	ADCS	ROVIZ
~50 k	45 s	44 s		37 s
~100 k	49 s	46 s	61 s	
~200 k	55 s			52 s

→ For the DSKs from both techniques, the efficiency is comparable to DSKs created by other tools.

Summary

- Lower case filenames
- No mentioning of MOC shape models
- Very sparse description of techniques

2 Consistency between plate models and images

- For the rendered images, no camera parameters, surface model, or illumination information is provided.
- ✓ For both techniques, all resolutions, and all viewing directions, the provided rendered images are consistent with the respective plate shape models.

- ✓ For both techniques, the DSKs are consistent with the plate shape models.

4 Consistency between the shape models

- × For both techniques, the shape models are not provided in the Cheops frame.
- Because of that, a quantitative analysis of the shapes themselves is pending.

5 Efficiency of the DSKs

- ✓ For the DSKs from both techniques, the efficiency is comparable to DSKs created by other tools.